

## A2

## JAXA における宇宙デブリ研究の概要

### Overview of JAXA's research on Space Debris

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**Ryoichi IMAI, vice president of JAXA, Director General,  
Research and Development Directorate**

JAXA は、国際社会との連携を取りながら、デブリの脅威を無くすための研究開発に総合的に取り組んでいる。JAXA のデブリ研究内容は、以下の 3 項目に大別される。

- 1) デブリの観測技術の向上による宇宙機運用の安全性確保
- 2) デブリによる宇宙機への衝突影響を最小化するための防護技術の開発とシステムのロバスト化設計
- 3) デブリ除去技術の研究開発と実現に向けた軌道上実証の検討

本講演では、JAXA におけるこれら研究開発の目的と現状について概観する。

JAXA is working in a comprehensive manner to eliminate the threats of space debris through the R&D and the cooperation with the international community.

Studies on Space Debris in JAXA consist in three major R&D subjects as follows.

- 1) Observation technology to contribute to the safety of the spacecraft operations
- 2) Protection and robust design techniques to minimize the impact on spacecraft by space debris
- 3) Active space debris removal and in-orbit demonstration

Objectives and status of these studies are overviewed in this presentation.

### **Biography**

#### **Ryoichi IMAI**

Vice President

Director General, Research and Development Directorate

Mr. Ryoichi Imai was appointed to Vice President of JAXA in 2015. He is in charge of Research and Development Directorate and is also Center Director of Tsukuba Space Center of JAXA.

He received Bs.degree in Physics and Ms.degree in Electrical Engineering from Kyoto University and joined National Space Development Agency of Japan (NASDA) in 1981.

He has been mostly involved in the research and development of Engineering Test Satellites through his carrier in NASDA and JAXA. He was also served to the development of the government satellites as a project manager.

In conjunction with his carrier in NASDA and JAXA, he was a visiting scholar in University of California in 1989 to make research in space robotics and was a senior researcher in National Communications Research Laboratory to make research in high speed satellite communications system in 1996-1998.



# Overview of JAXA's research on Space Debris

Oct. 18, 2016  
The 7th Space Debris Workshop

Ryoichi IMAI, JAXA

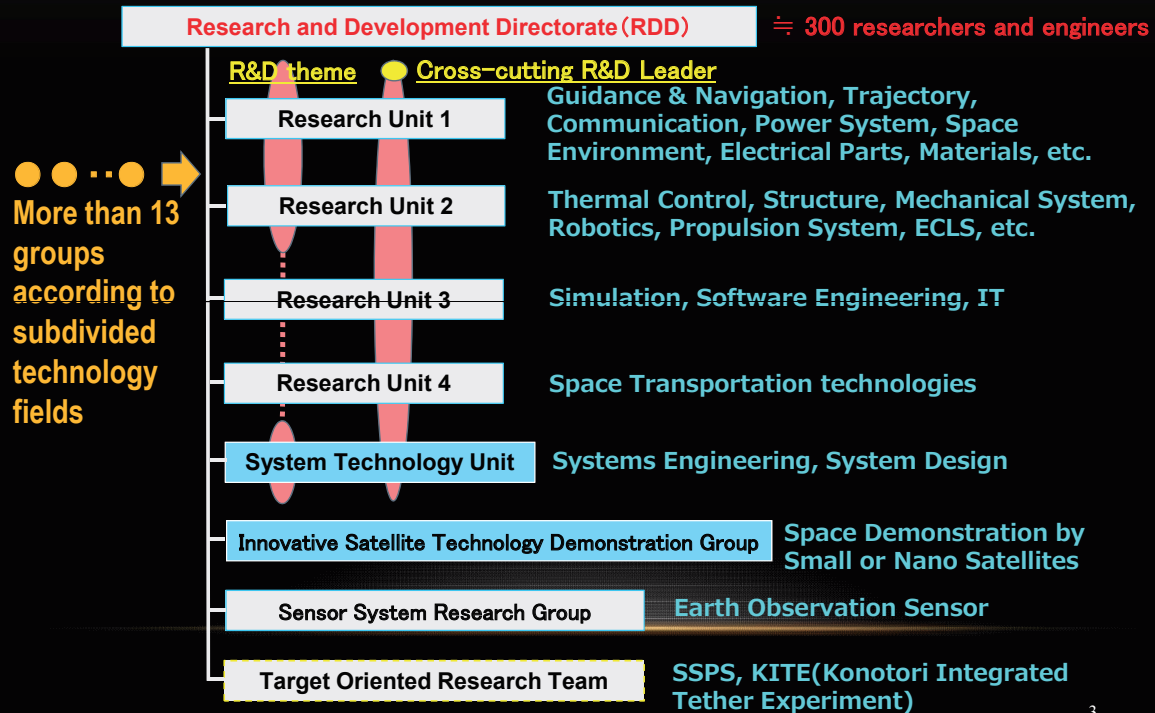
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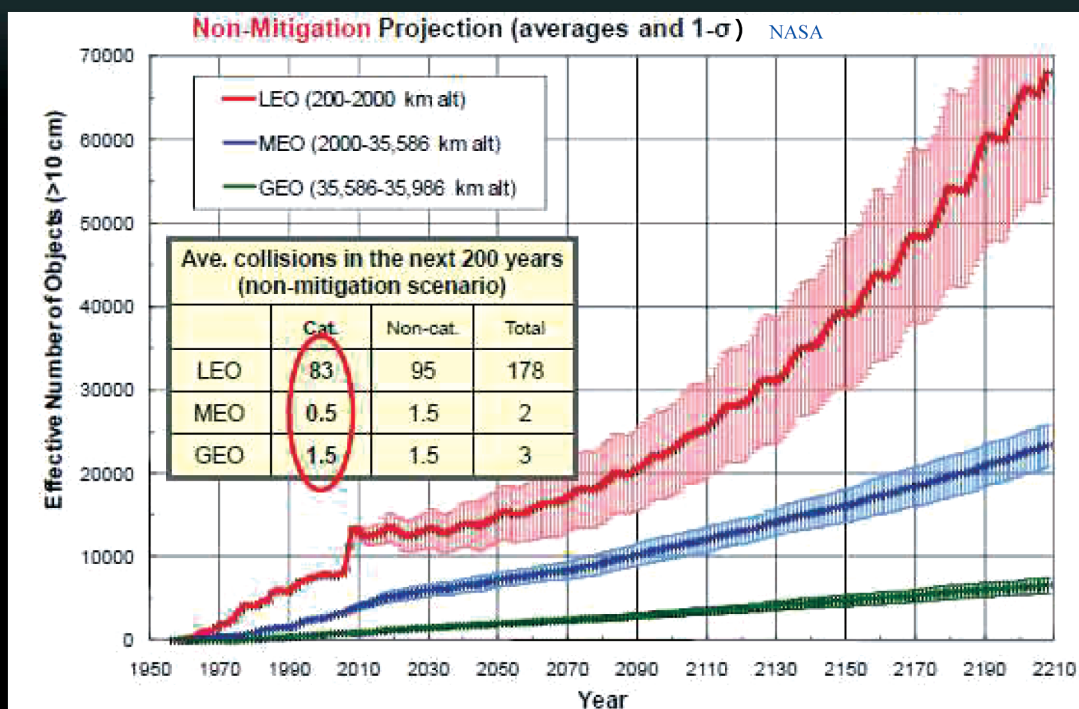
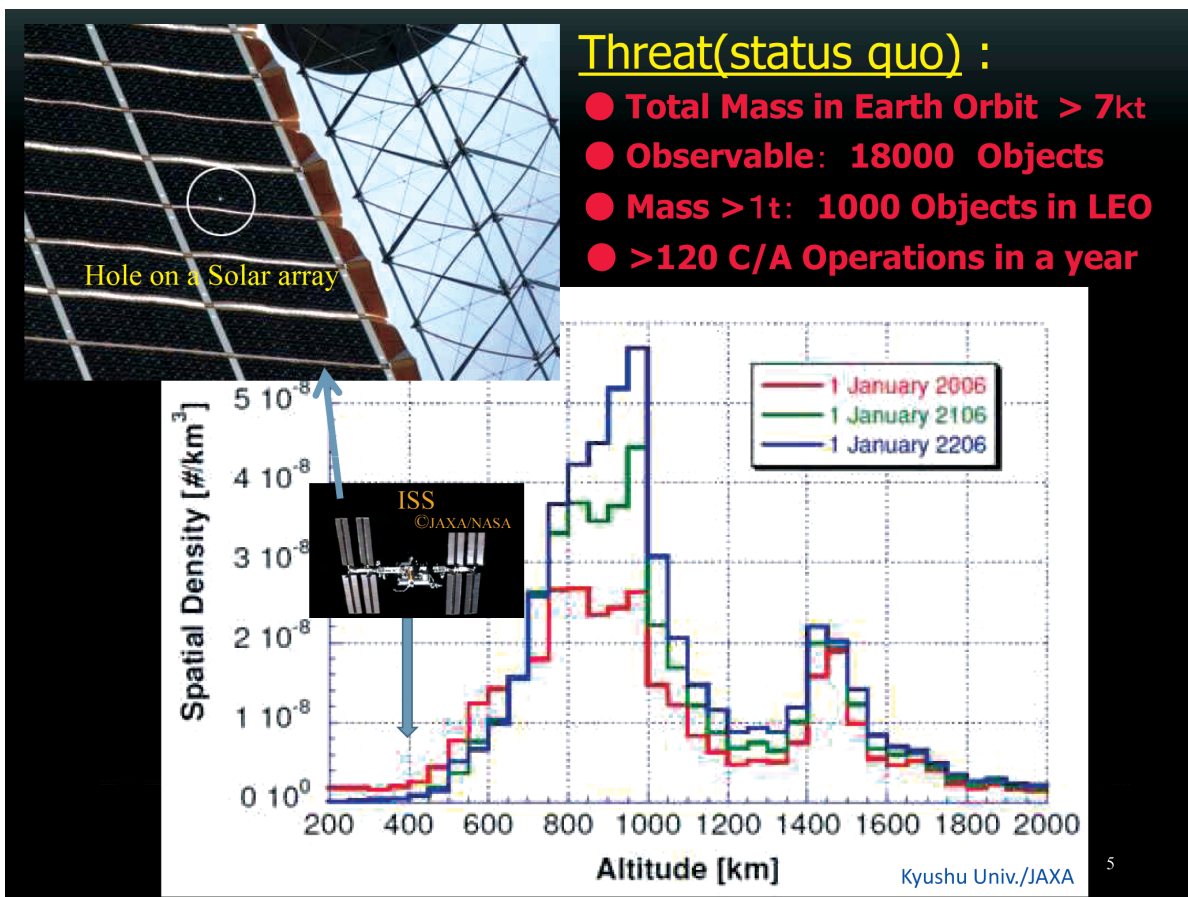
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- R&D organization was reformed to strengthen the cross-cutting research activities for creating the innovative technologies



## 1. Background

- Basic Plan on Space Policy :
    - Promoting the international activities to draw up the ICOC (International Code of Conduct for Outer Space Activities)
    - Improving the capability of SSA
    - Addressing the R&D on debris removing technologies
  - JAXA's contribution and R&D activities :
    - Proposing the technical guidelines for debris mitigation through the activities on IADC (Inter-Agency Space Debris Coordination Committee).
    - Taking advantages of Japan's strengths and promoting the research and development on the space debris mitigation technologies such as observation, protection and safety removal.
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Observable : > 10cm (LEO)  $\Leftrightarrow$  Possible protection size < a few millimeters

**R&D Challenges**



## 2. R&D activities for Space Debris :

### ● Situational Awareness and Defense

- ⇒ Ground Observation and In-Orbit Observation
- ⇒ Maneuver Planning
- ⇒ Modeling
- ⇒ Protection

### ● Mitigation

- ⇒ Safe re-entry( Post mission disposal and ground safety)

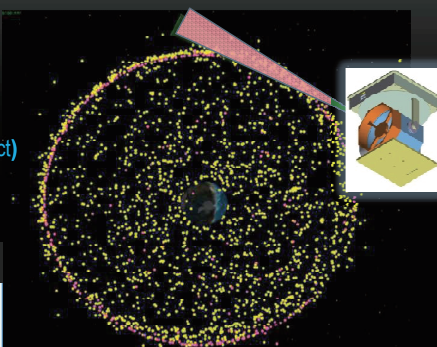
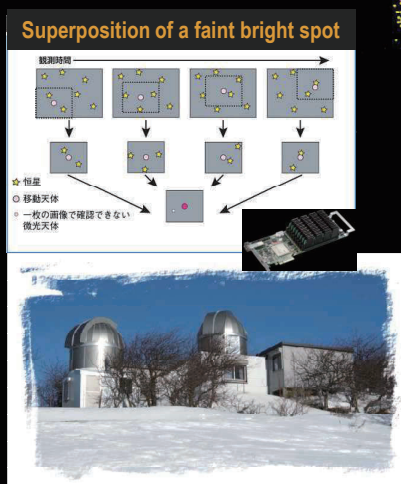
### ● Removal

- ⇒ Cost-effective removal scenario
- ⇒ Technologies
- ⇒ EDT Experiment using HTV-6 (2016)

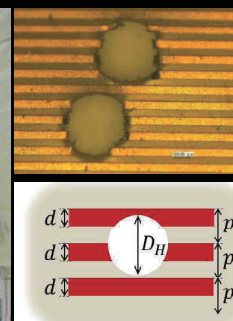
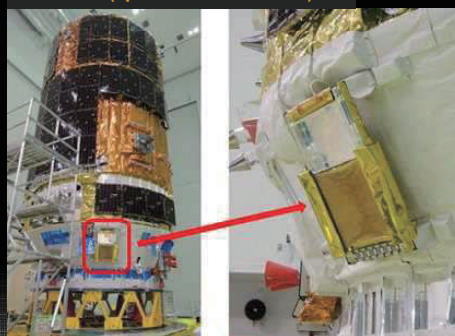
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### ● Observation From Ground

- Optical  
(Discovery of un-cataloged object)
- Radar



HTV-5 (space debris monitor)



### ● Observation In Orbit

- Onboard Camera  
(GEO, >1cm)
- Impact sensor  
(LEO, >0.1mm)

⇒ Goal: Seamless Mapping

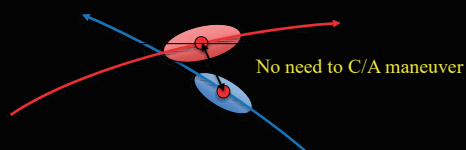
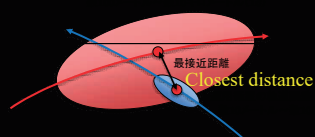
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## ● Maneuver Planning

Because of the low determination accuracy of debris orbit, there is a high uncertainty to estimate the collision risk.

Increasing number of space debris makes higher the operation load of collision avoidance.

- Current Criteria : Radial distance of 200m and total miss distance of 1000m

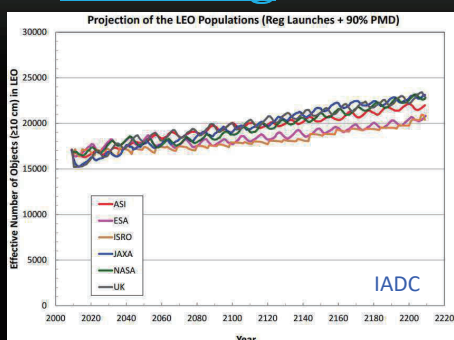


⇒ Improving the orbit determination and prediction of space debris

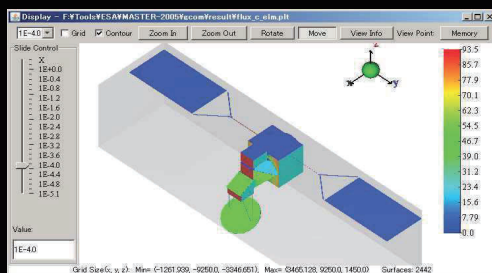
- Embark the development of new observatory (Radar & Optical)
- Modeling the determination error with the operation history data

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## ● Modeling



Transition Prediction of Debris environment



Collision probability and effects estimation

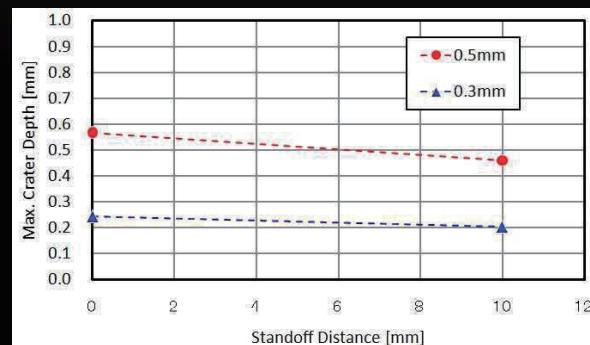
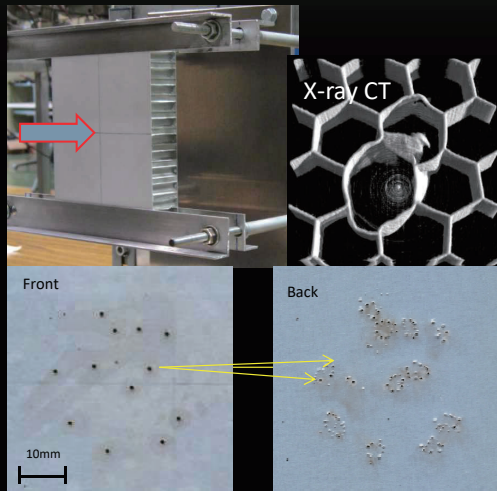
## JAXA develops debris related models and tools

- To predict the future changes in the number of debris : "debris evolutionary model" (developed in collaboration with Kyushu University)
- To assess the probability of damage caused by debris collision: "debris collision damage analysis tool"
- To assess the compliance with debris mitigation standards: "debris mitigation standard support tools"

⇒ Reflected in the design rules for spacecraft as well as in the regulatory rules for debris prevention

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## ● Protection



At the 10mm away point from the outer skin, the energy of impact will be reduced by 15-20%

Ref. Higashide, et al., Trans. JSASS Aerospace Tech. Japan, 2012

Collision Test to the honeycomb sandwich panel

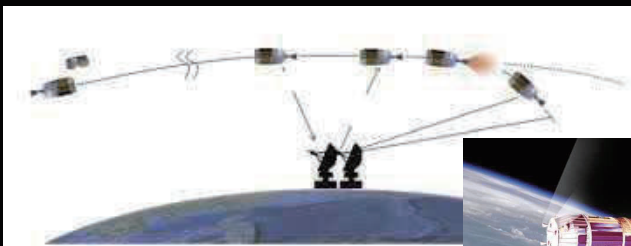
- Object of 1mm  $\phi$  with the velocity of 10km/sec
- AL-Skin Honeycomb Panel :  $t_{\text{skin}}=0.25\text{mm}$ ,  $h_{\text{core}}=25.4\text{mm}$

⇒ Reflected in the design guidelines and the damage evaluation

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## ● Mitigation

- Compliance with 25 years rule and Controlled reentry
- Data acquisition of the re-entry stage .
- Utilization of the advanced carbon-fiber composite materials
  - Fuel tank is melted during re-entry



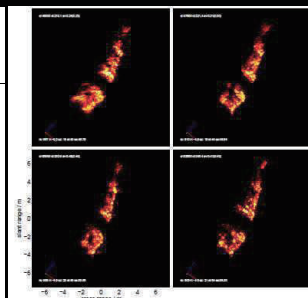
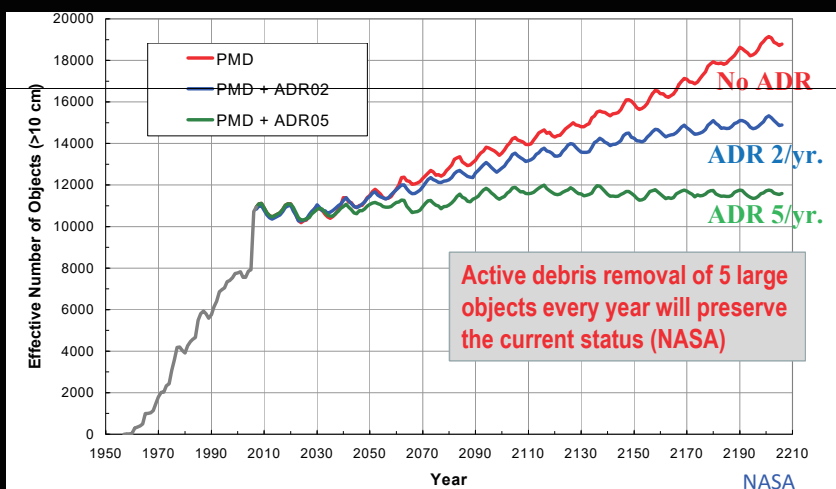
⇒ To secure ground safety

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## ● Active Debris Removal (ADR)

- Removal of large objects in congestion orbit is effective
- More than Half of them are upper stages of launch vehicles
- Upper stages are simple in shape and stable in motion

⇒ Upper stages are most effective and urgent target for ADR



FGAN image of H-2A second stage : Stabilized by gravity gradient

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## ● Challenges in ADR

Implementation scenario

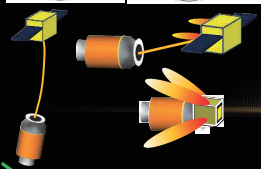
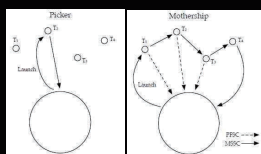
( Property, Liability, Business viability )

Technical subjects

( Capture of non-cooperative target )

Research subjects

① Scenario



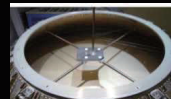
② Propulsion



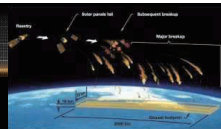
③ GN&C



④ Capture



⑤ Deorbit & safety re-entry



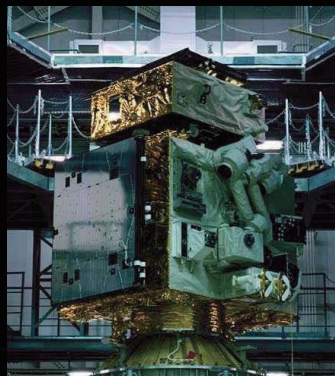
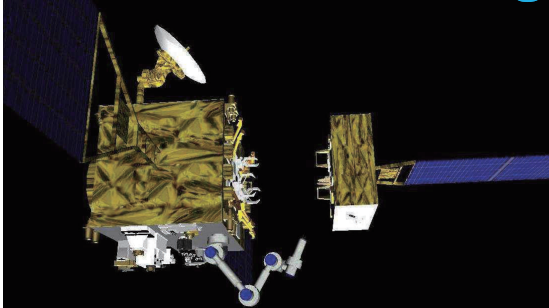
⑥ Ground Test & Simulation



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## ● Technical Heritage in JAXA



ETS-VII (1997-1999)



HTV (2009- )



Hayabusa  
(2003-2010)

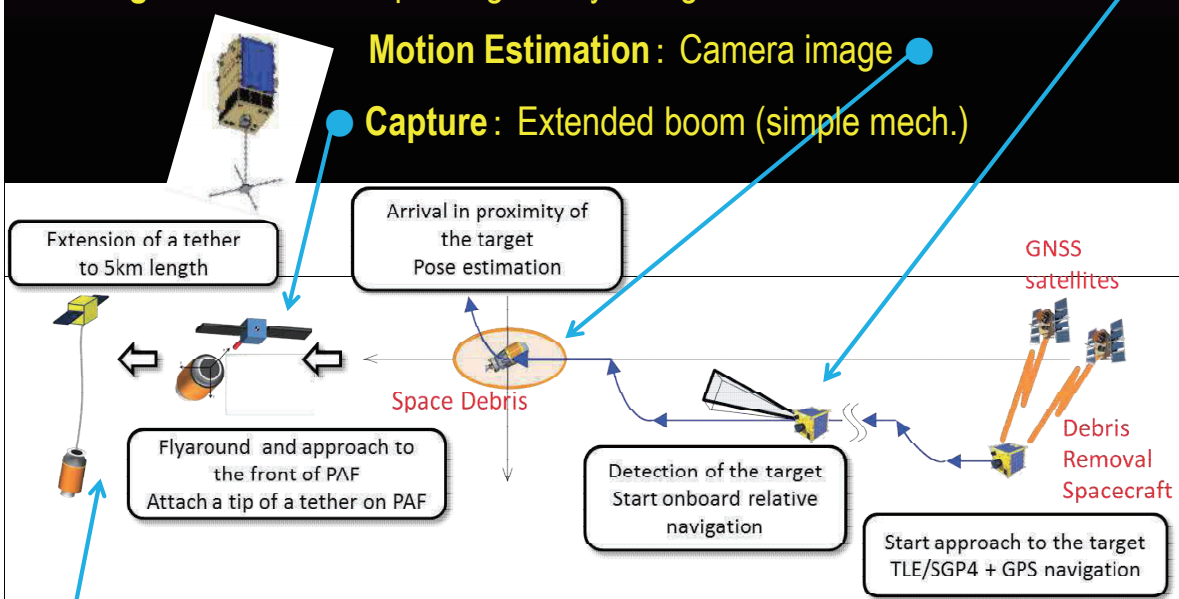
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## ● Basic Strategy of Upper Stage Removal

**Navigation:** AON (simple Angle Only Navigation with Vis & IR Camera)

**Motion Estimation:** Camera image

**Capture:** Extended boom (simple mech.)



**Deorbit:** EDT (No-fuel) ⇒ **Goal: Reliable and low cost system**

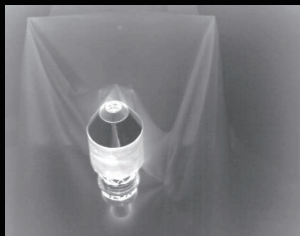
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## ● Vision based Navigation

- Navigation Target : Circular structure image of PAF (Payload Attachment Fitting)
- Testing the relative navigation and motion estimation using the Camera Image under the various lighting conditions.



Visible Camera Image



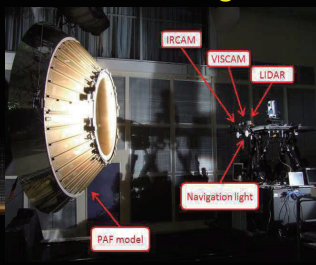
IR Camera Image



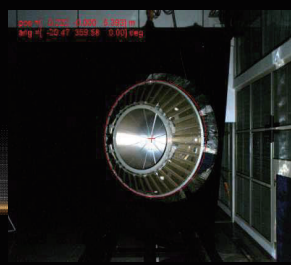
Earth background (Chroma key)



Lighting simulator



Visual Navigation motion simulator



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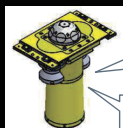
## ● EDT experiment using HTV-6 (2016)

Electrodynamic  
Tether  
Length: 700m  
Collecting the  
electron and  
Producing the  
Lorentz Force

### Tether

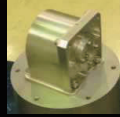


### End Mass



Reflector

### Brake



### Spool



### End Mass Deployment Pod

Deployment  
Velocity: >1m/s



### Visual Camera



Monitoring the motion  
of End Mass

### Rendezvous sensor

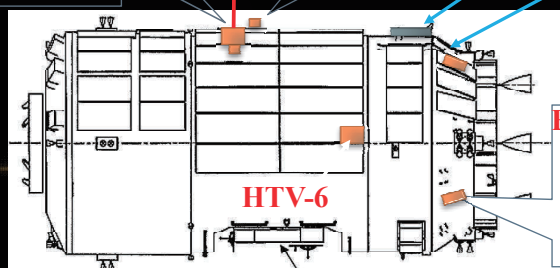
### Charging Monitor

Measurement of Plasma potential  
and Induced electromotive force

### Electron Emission (FEC)

Generate the  
10mA  
Tether  
electrical  
current

X  
Y  
Z



HTV-6

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### 3. Conclusion :

- JAXA is promoting the comprehensive approach to Space Debris Mitigation
- The primary goal of JAXA is to secure the safety of the space activities.
- In particular, JAXA focuses on the R&D of the practical technologies for removing the large space debris in the congestion orbit.
- Cooperation with international partners and private companies is important for feasible and sustainable activities.

**Thank you for your attention**

**ご清聴ありがとうございました**