

C13

東京大学木曾観測所広視野 CMOS モザイクカメラ Tomo-e Gozen による人工天体の観測

Observations of Artificial Objects with a wide-field CMOS mosaic camera: Tomo-e Gozen

大澤亮, 酒向重行, 小島悠人(東京大学), 奥村真一郎, 浦川聖太郎(日本スペースガード協会), 柳沢俊史, 吉川真(JAXA), Tomo-e Gozen サイエンスグループ

Ryou Ohsawa, Shigeyuki Sako, Yuto Kojima (Univ. Tokyo), Shin-ichiro Okumura, Seitaro Urakawa (Japan Spaceguard Association), Toshifumi Yanagisawa, Makoto Yoshikawa (JAXA) and Tomo-e Gozen Science Group

東京大学木曾観測所では 105-cm シュミット望遠鏡に搭載する広視野 CMOS モザイクカメラ Tomo-e Gozen の開発を進めている。Tomo-e Gozen は 4 つのモジュールから構成されるカメラである。各モジュールに 21 枚、合計 84 枚の CMOS イメージセンサを搭載する。20 平方度の領域を 2 Hz でモニタリングする能力を持ち、恒星に対する限界等級はおよそ 18.5 等である。また、部分読み出しをすることで、より速いフレームレートでの観測も可能である。こうした性能から Tomo-e Gozen は微小なスペースデブリの発見やデブリの運動状態の決定に高いパフォーマンスを発揮すると考えられる。2018 年 2 月には 1 つのモジュールを用いて機能試験観測を実施した。現在では 21 枚のイメージセンサでサーベイ観測試験を進めている。また残りのモジュールの開発も進行中である。発表では地球接近小惑星や人工衛星の観測結果を紹介とともに、スペースデブリ監視への貢献可能性について議論する。

We are developing a new wide-field mosaic CMOS camera, Tomo-e Gozen, for the 105-cm Kiso Schmidt Telescope at Kiso Observatory, the University of Tokyo. Tomo-e Gozen is composed of four individual camera modules, each of which has 21 CMOS image sensors. Equipped with the 84 CMOS image sensors in total, Tomo-e Gozen is able to monitor a sky of about 20 sq-degree at up to 2 Hz. The limiting magnitude for stars is about 18.5 mag. Frame rates faster than 2 Hz are available by narrowing the field of view. Tomo-e Gozen is expected to show high performances in detecting tiny space debris and deriving the motion of space debris. The development of the first camera module Q1 was completed in February, 2018. In the experimental observations, the camera was successfully operated with the 21 CMOS image sensors. Currently, a high-cadence wide-area survey is in operation. We'll present some observations of near earth asteroids and artificial objects with Tomo-e Gozen, and discuss possible contributions of Tomo-e Gozen to the surveillance and tracking of space debris.

8th Space Debris Workshop in JAXA
**Observations of Artificial Objects
with a wide-field CMOS mosaic camera: Tomo-e Gozen**

Ryou Ohsawa, Shigeyuki Sako, Yuto Kojima (U. Tokyo),
Shin-ichiro Okumura, Seitaro Urakawa (JSKA),
Toshifumi Yanagisawa, Makoto Yoshikawa (JAXA),
and Tomo-e Gozen Science Group

Tomo-e Gozen

The world largest video camera (84 CMOS sensors+ 1.0 m telescope)

Suitable specifications to characterize/detect debris

- Wide field-of-view — 20 deg² sky coverage with 1.2"/pixel
- High sensitivity — stars of 18 mag detected in 2 Hz observation
- High time-resolution — 2 Hz observation, higher framerate available by partial readout
- Accurate timestamp — synchronized with the GPS time, accurate to ~0.2 ms

Operating with a limited performance / Full operation is scheduled in 2019

Performance of Tomo-e Gozen in debris observations

Detection limits: ~30 cm board & ~3 mm mirror in GEO / ~ 5 cm namecard in LEO

Follow-up capability:

sub-second time-resolution lightcurve reveals the shape and motion of debris

Daily moving object survey:

detect ~1,000 high-speed (>1"/s) objects and self follow-up in 2 hours

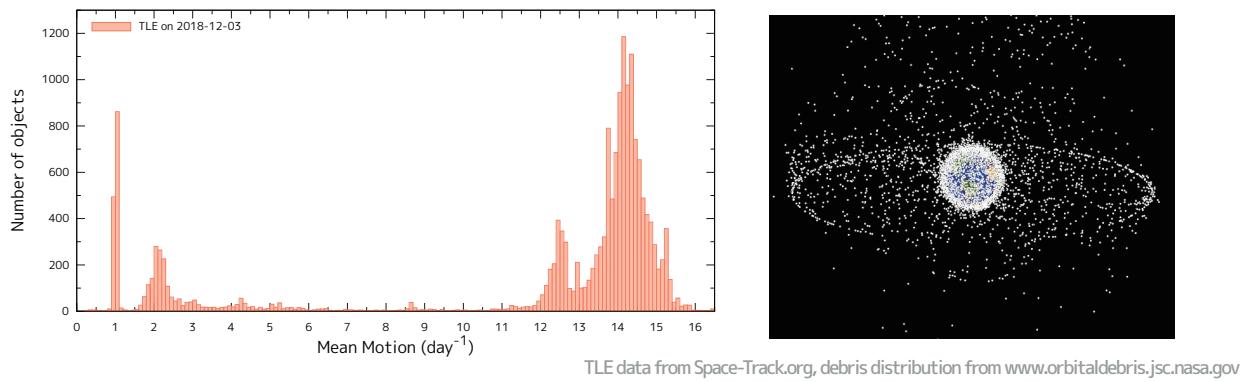
1. Ground-based observations of orbit debris
2. Tomo-e Gozen project
3. Examples from observations with Tomo-e Gozen

Backgrounds

More than 17,000 objects orbiting around the Earth are identified

Observable characteristics: the size, orbit, and motion of orbit debris

understanding the population of space debris
removal missions of orbital debris



Backgrounds

Ground-based optical observations:

Only available in night time

Brightness \propto distance $^{-2}$ (c.f. \propto distance $^{-4}$ in radar observation)

Advantages in observations of distant small debris

Preferred specifications of telescopes and cameras

Erroneous ephemeris — wide field-of-view

Size ~ brightness — high sensitivity

Moving & rotating — high time-resolution

Fast movement — accurate timestamp

Tomo-e Gozen project

A mosaic CMOS camera at Kiso Observatory, the University of Tokyo

Tomo-e Gozen project

A mosaic CMOS camera at **Kiso Observatory**, the University of Tokyo



Blank map from www.wikimedia.org, detailed map from www.google.com/maps

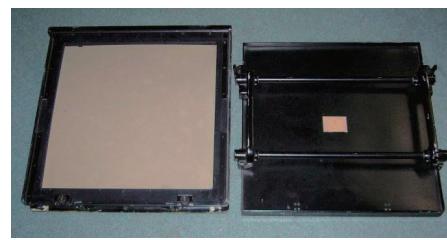
Tomo-e Gozen project

A mosaic CMOS camera at **Kiso Observatory**, the University of Tokyo

1.05 m Schmidt-type telescope (Kiso Schmidt)

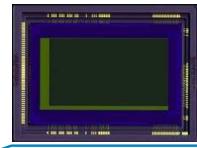
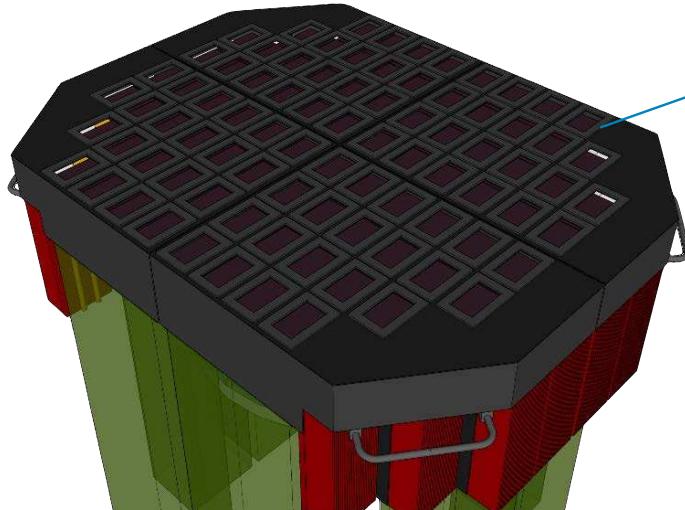
Designed for observations with photographic plate

Extremely wide field-of-view ($\phi \sim 9^\circ$)



Tomo-e Gozen camera

A wide-field mosaic CMOS camera for Kiso Schmidt telescope



2Kx1K CMOS image sensor by **Canon**

84 CMOS sensors covering $\sim 20\text{deg}^2$

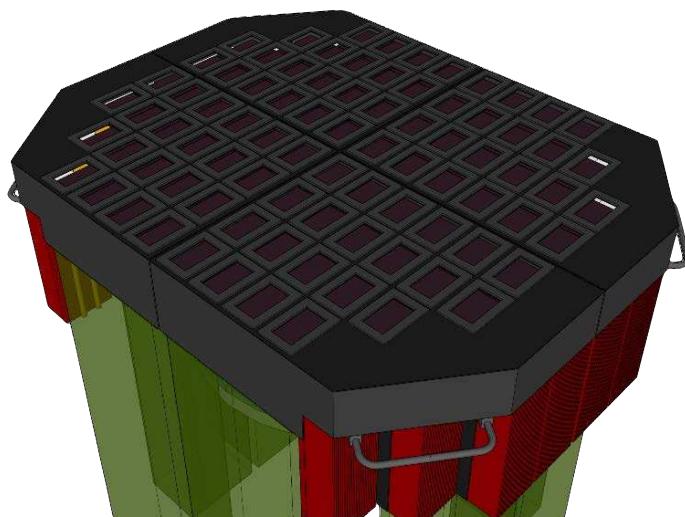
Composed of four camera modules

Continuous monitoring at 2 Hz

High-speed observation by partial readout

Tomo-e Gozen camera

A wide-field mosaic CMOS camera for Kiso Schmidt telescope

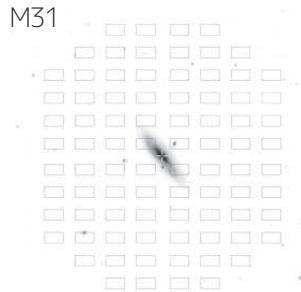


Specifications (Sako et al. Proc. SPIE, 2018)

| | |
|----------------------|---|
| Observatory | Kiso Observatory |
| Telescope | 1.0-m f/3.1 Schmidt telescope |
| Sensor format | 2160×1200pixchip ⁻¹ |
| Field of view | 39.7×22.4 × 84 chips ($\sim 20\text{deg}^2$) |
| Pixel scale | 19 μm , 1".189pix ⁻¹ |
| Wavelength | 350–700nm (peak at 500nm) |
| Filters | optical broadband (transparent) |
| Frame rate | 2Hz (max, continuous, full frame) |
| Read noise | ~1.9e ⁻ at 2Hz |
| Dark current | ~0.1 e ⁻ sec ⁻¹ pix ⁻¹ at 277K |
| Well depth | ~6,400e ⁻ |
| 5 σ lim. mag. | ~18.5 mag. in 0.5 sec exposure |

Tomo-e Gozen camera

Brief summary of the specifications of the Tomo-e Gozen



The world largest video camera (84 CMOS sensors+ 1.0 m telescope)

Located at $35^{\circ} 47' 50.0''$ N, $137^{\circ} 37' 31.5''$ E

Distinctive specifications:

20 deg² sky coverage with 1.2"/pixel

stars of **18 mag** detected in 2 Hz observation

2 Hz observation, higher framerate available by partial readout

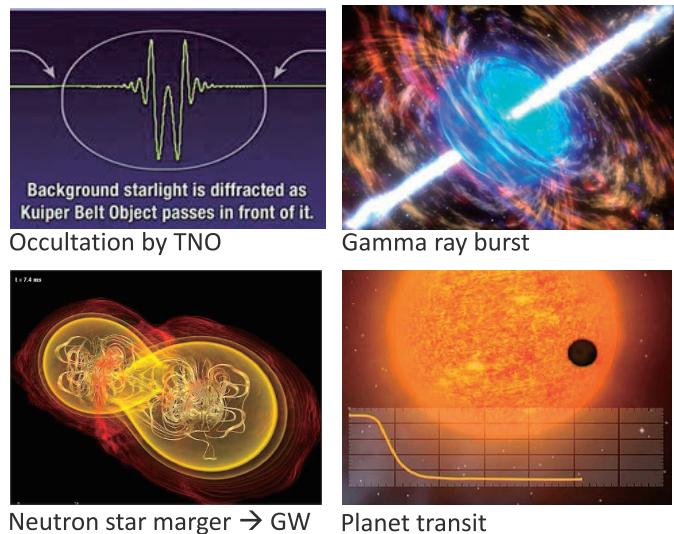
synchronized with the **GPS time**, accurate to ~0.2 ms



Science Cases of Tomo-e Gozen

Rare & Fast Transient Phenomena

- + Shock Breakout of core-collapse SN
- + Optical follow up of Gravitational wave
- + Optcal counterpart of fast radio burst
- + Explosion of nova
- + Afterglow of gamma-ray burst
- + X-ray time variable objects
- + Transit of Exoplanet
- + Occultation by Trans-Neptunian object
- + Potentially Hazardous Asteroid
- + Faint meteor



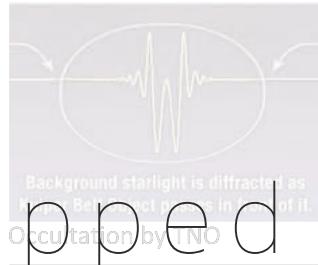
From the presentation by S. Sako in the Kiso Schmidt symposium 2016

Science Cases of Tomo-eGozen

Rare & Fast Transient Phenomena

- + Shock Breakout of core-collapse SN
- + Optical follow up of Gravitational wave
- + Optical counterpart of fast radio burst
- + Explosion of nova
- + Afterglow of gamma-ray burst
- + X-ray time variable objects
- + Transit of Exoplanet
- + Occultation by Trans-Neptunian object
- + Potentially Hazardous Asteroid
- + Faint meteor

Skippped



From the presentation by S. Sako in the Kiso Schmidt symposium 2016

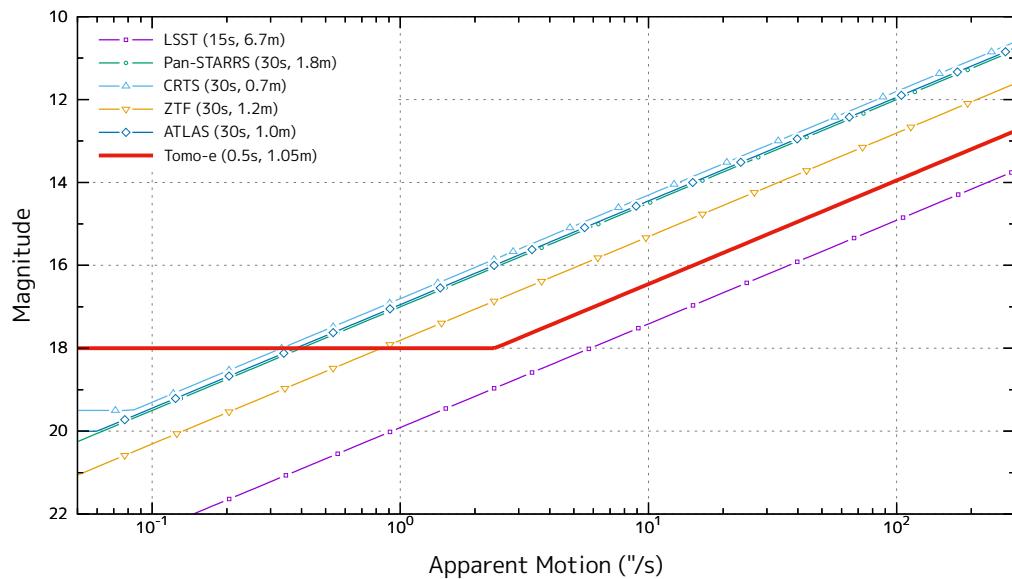
Example: Catalina C/2013 US10



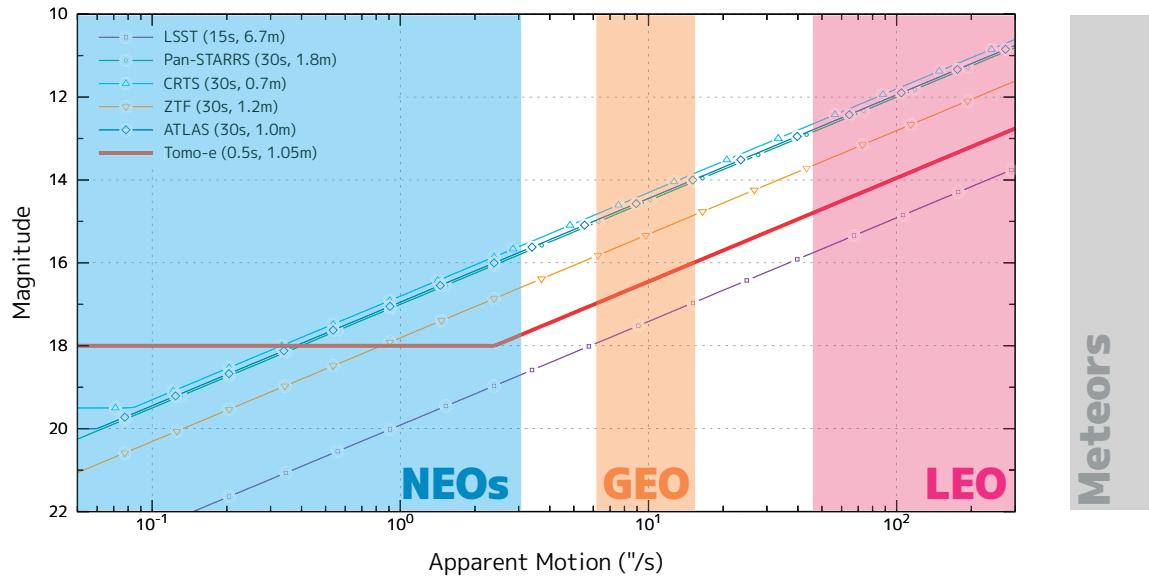
Example: Meteor trail



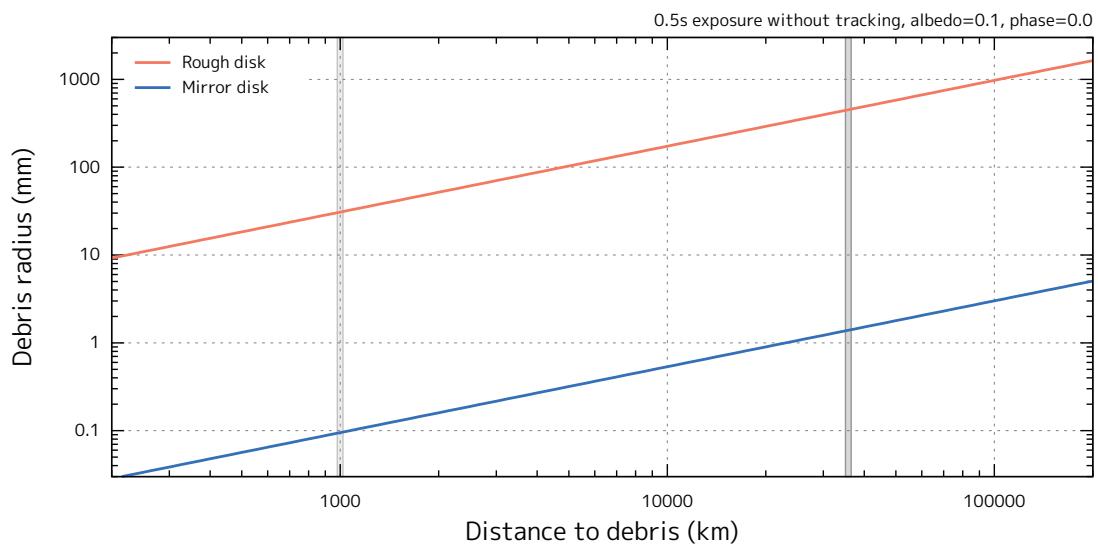
Comparing with other facilities



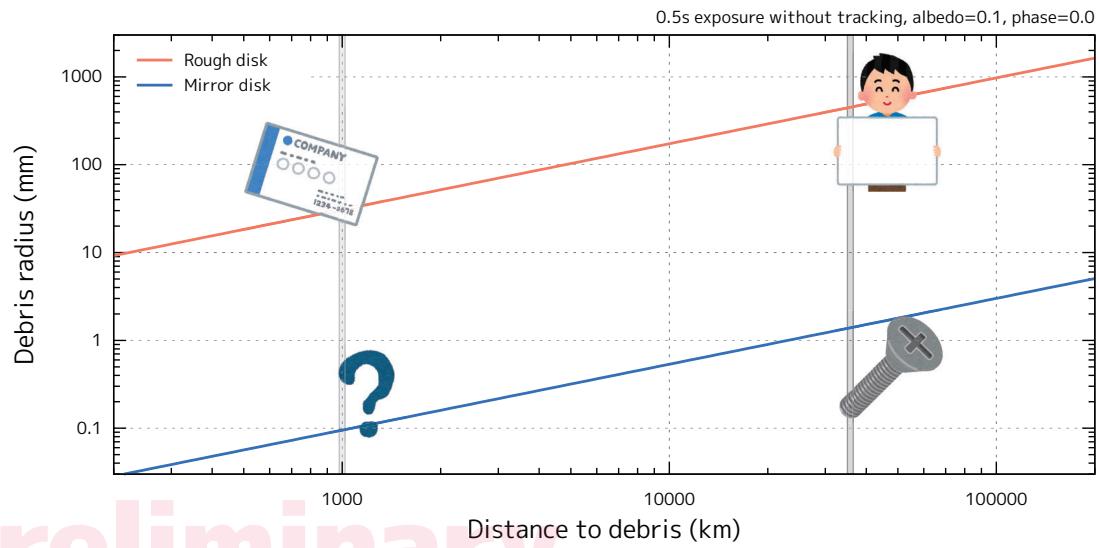
Comparing with other facilities



Detection Limits in 2 Hz



Detection Limits in 2 Hz



Preliminary

Flash detected by Tomo-e Gozen



1. Follow-up/monitoring observations
2. Blind survey of moving objects

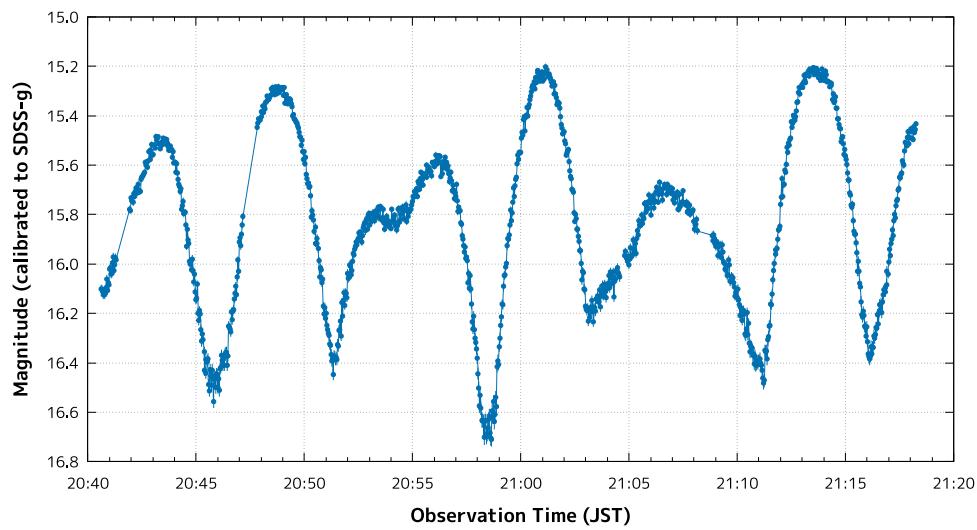
1. Follow-up/monitoring observations

2. Blind survey of moving objects

Observation of NEO: 2012 TC₄



Observation of 2012 TC₄

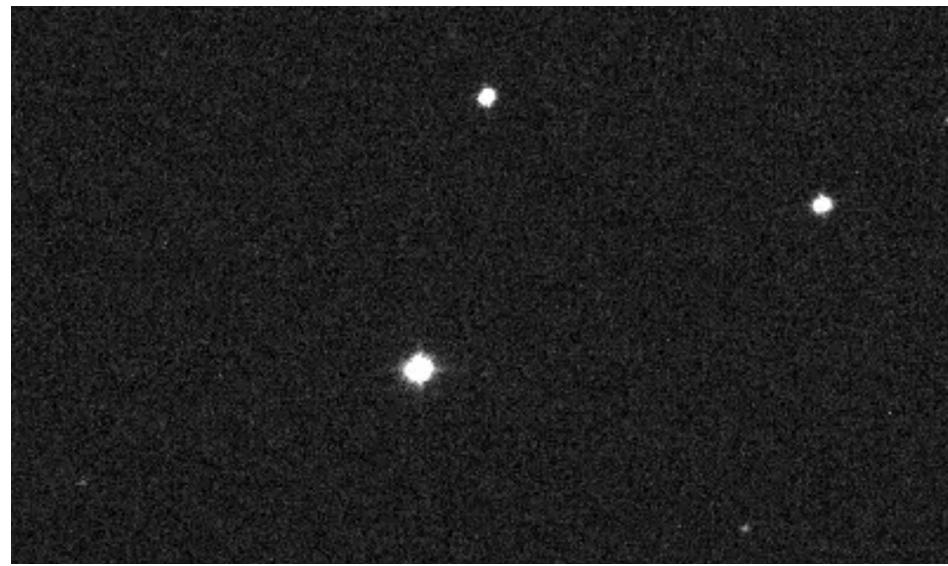


Data from Urakawa et al., submitted

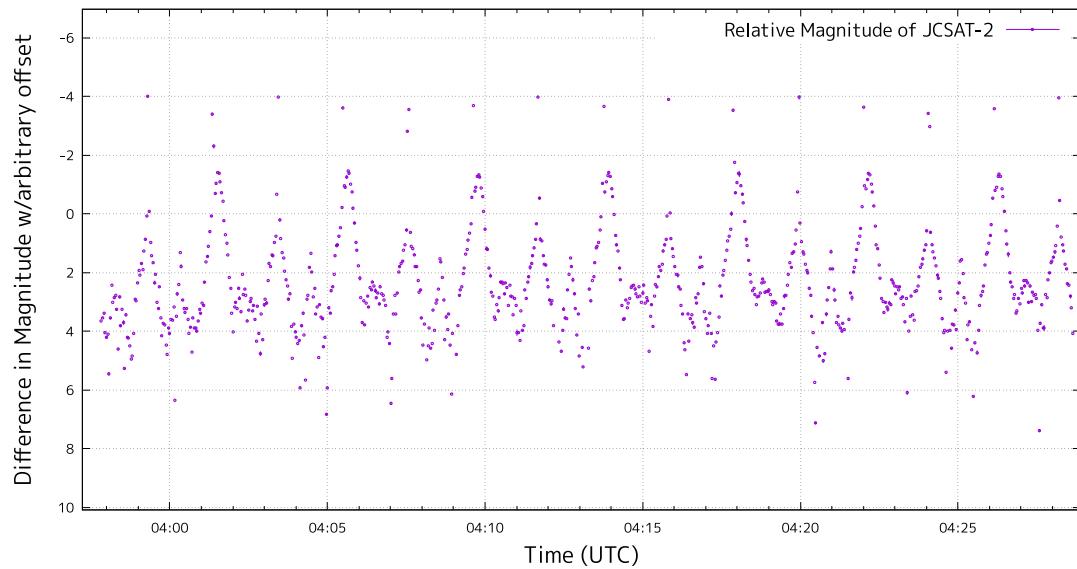
Observation of 2012 TC₄



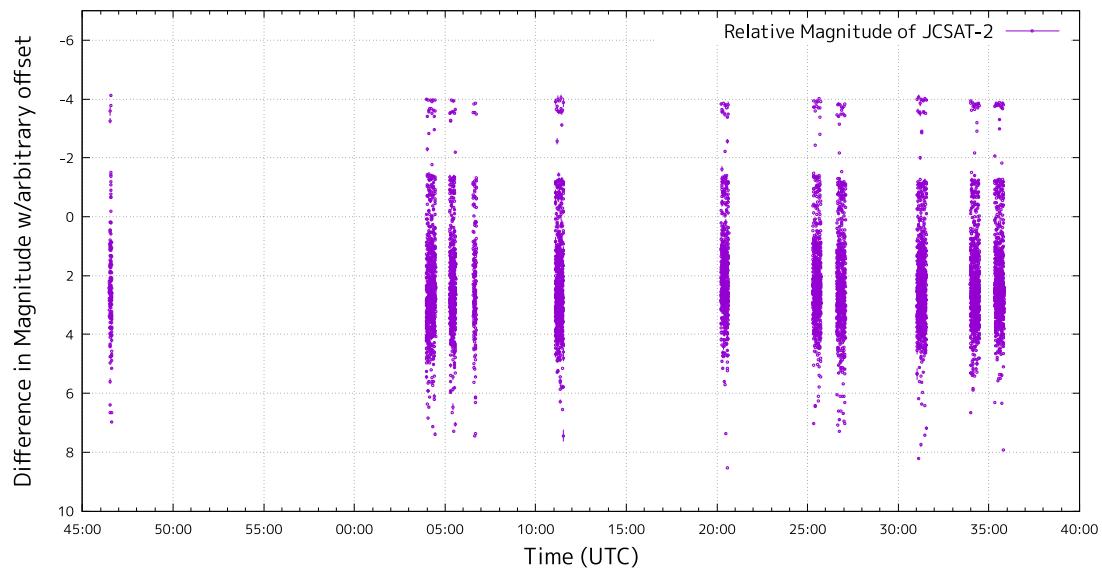
Observation of JCSAT-2



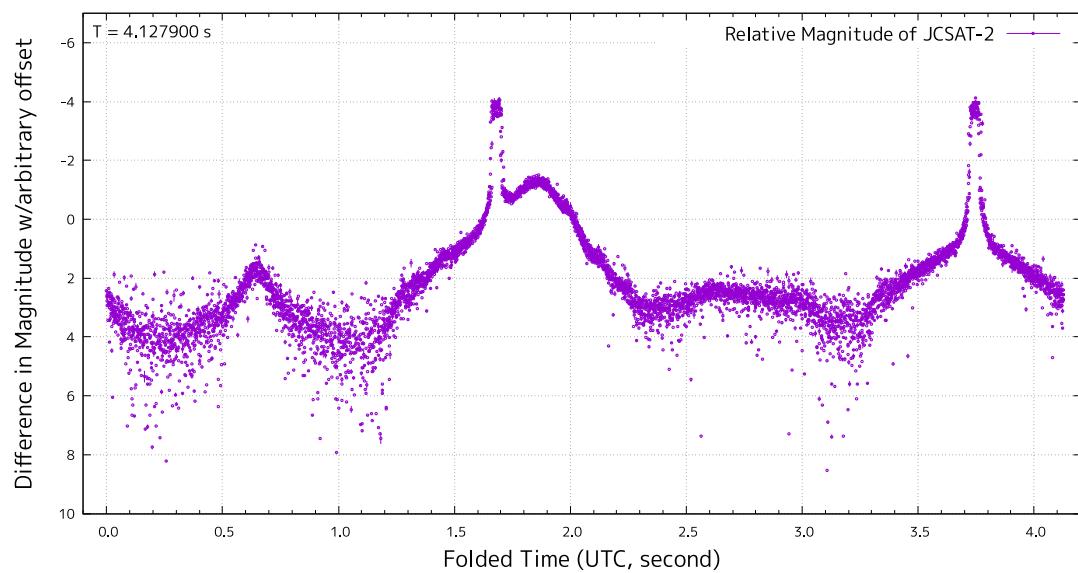
Observation of JCSAT-2



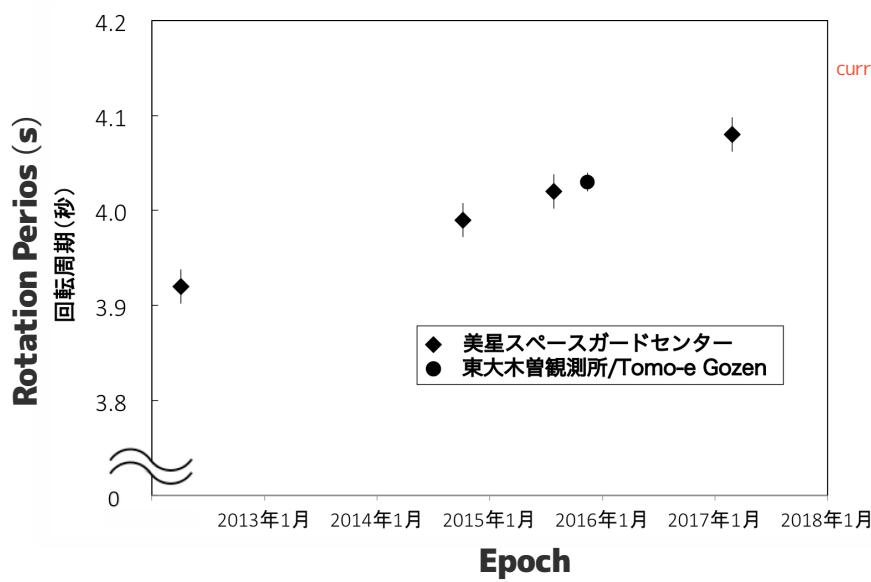
Observation of JCSAT-2



Observation of JCSAT-2



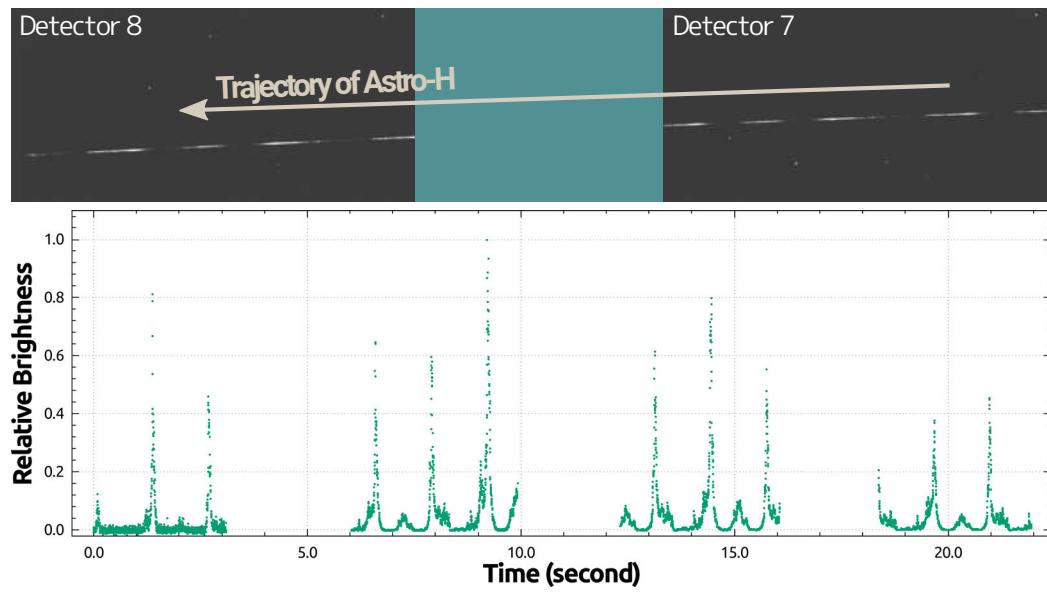
Observation of JCSAT-2



Observation of Astro-H



Observation of Astro-H



1. Follow-up/monitoring observations

2. Blind survey of moving objects

by Yuto Kojima (Univ. Tokyo)

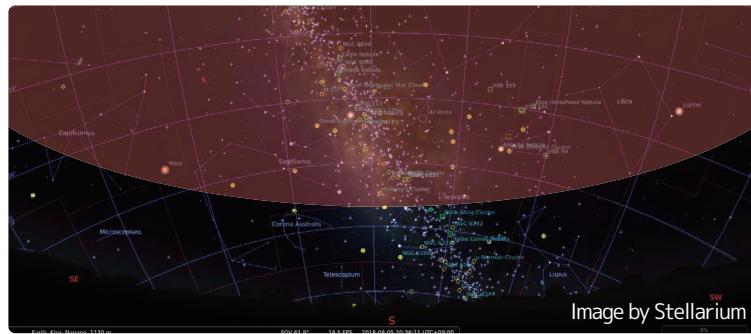
Tomo-e Gozen Supernova Survey

Tomo-e Gozen is originally developed to detect explosions in the Universe.

Take a 6-second video, move the telescope, take a 6-second video, and

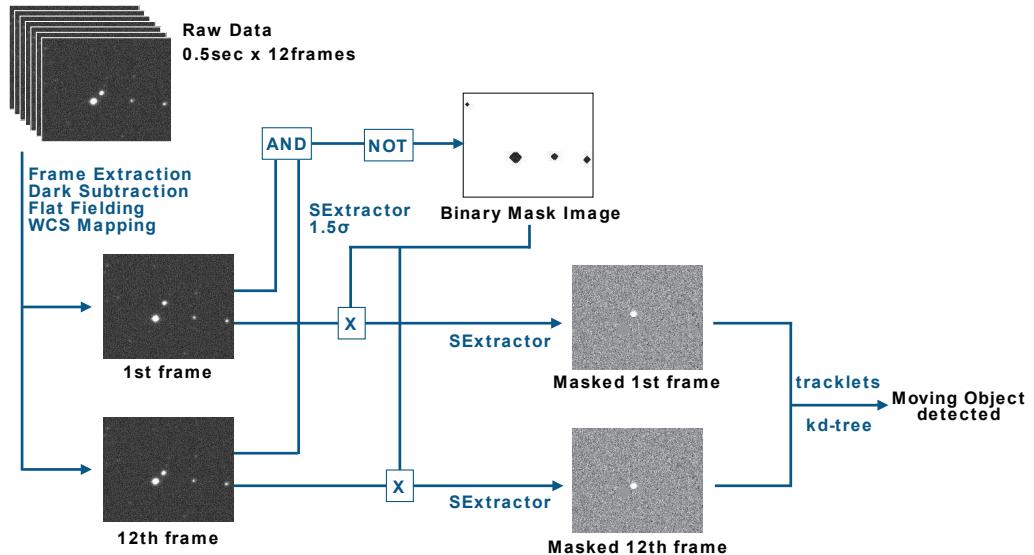
Patrol the entire visible sky at least twice in a night.

⇒ this data are useful for a blind survey of moving objects



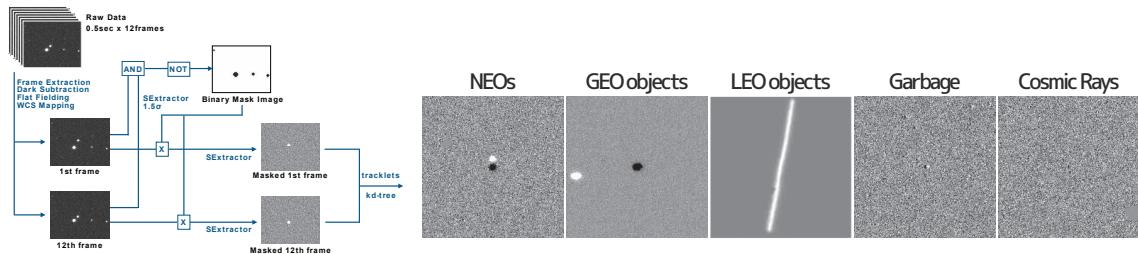
For the details of NEO detection system, refer to the master thesis by Yuto Kojima

Near-Earth Object Tomo-e Gozen Supernova Survey



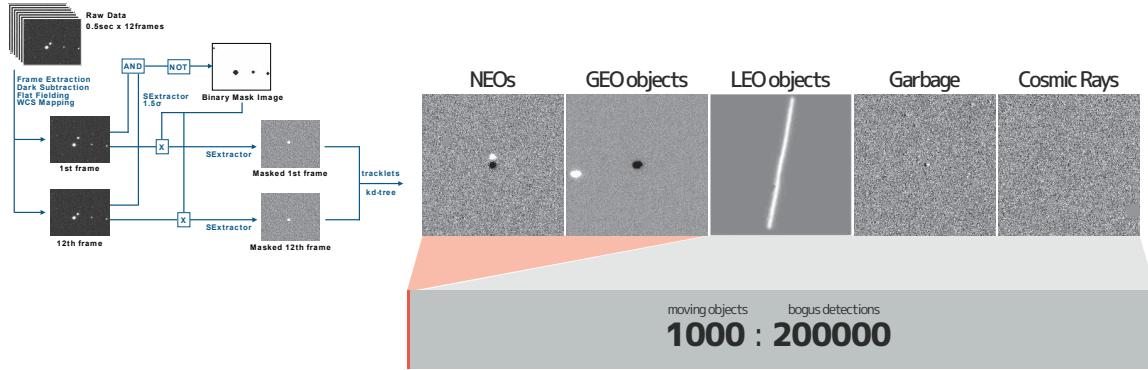
For the details of NEO detection system, refer to the master thesis by Yuto Kojima

Near-Earth Object Tomo-e Gozen Supernova Survey



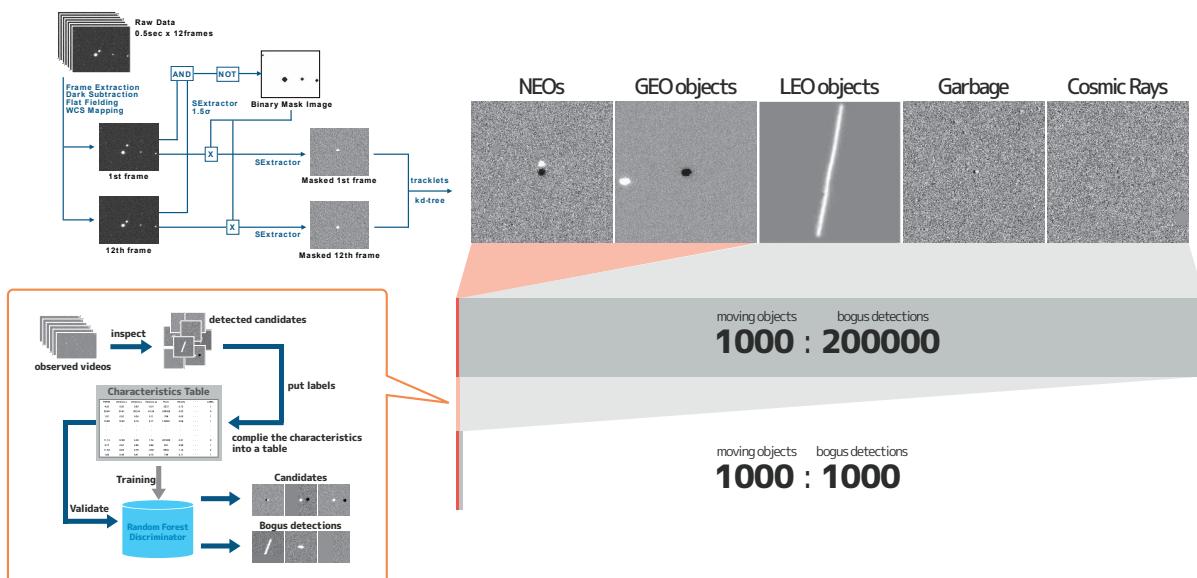
For the details of NEO detection system, refer to the master thesis by Yuto Kojima

Near-Earth Object Tomo-e Gozen ~~Supernova Survey~~



For the details of NEO detection system, refer to the master thesis by Yuto Kojima

Near-Earth Object Tomo-e Gozen ~~Supernova Survey~~



For the details of NEO detection system, refer to the master thesis by Yuto Kojima

Near-Earth Object Tomo-e Gozen ~~Supernova Survey~~

Tomo-e Gozen NEO Viewer

NEO candidates

detections: 1545

| No. | DATE(UTC) | Obj ID. | image | file | score | RA, DEC | Vx [pix/frame] | Vy [pix/frame] |
|------|-------------------------------|-------------|-------|------------------------------|-------|-----------------------------------|----------------|----------------|
| 1070 | 2018-12-01 16:55:01.353510 | 42157_126_6 | | rTMQ1201812010004215726.fits | 1.0 | 05h24m00.3529s +11d44m32.772s | 4.61 | 0.37 |
| 1261 | 2018-12-01 17:56:06.295714 | 42360_126_1 | | rTMQ1201812010004236026.fits | 0.999 | 07h33m47.7041s +26d45m53.3968s | 4.26 | 0.32 |
| 646 | 2018-12-01 14:37:09.120533 | 41677_123_3 | | rTMQ1201812010004167723.fits | 0.998 | 04h51m08.392s +09d25m32.7805s | 6.27 | 0.82 |
| 1112 | 2018-12-01 17:04:18.968920 | 42189_115_3 | | rTMQ1201812010004218915.fits | 0.998 | 03h10m31.5474s +03d40m01.6718s | 6.09 | 1.0 |
| 774 | 2018-12-01 | 41798_112_3 | | | | | | |

Near-Earth Object Tomo-e Gozen ~~Supernova Survey~~

Tomo-e Gozen NEO Viewer

Information of a NEO candidate 42157_126_6

| | |
|--|---|
| | UTC 2018-12-01 16:55:01.353510 |
| | RA,DEC 05h24m00.3529s +11d44m32.772s |
| | Vx 4.61 [pix/frame], 11.064 [°/sec] |
| | Vy 0.37 [pix/frame], 0.887 [°/sec] |
| | X 167.1116 [pix] |
| | Y 646.0013 [pix] |
| | Detection Threshold 1.7 |
| | Machine Learning Threshold 0.5 |

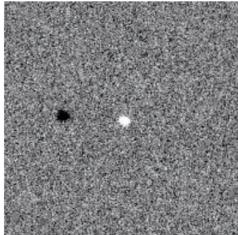
MPC format

| | | |
|-----------------|---|-----|
| First Detection | C2018 12 01.70487385 24 00.35 +11 44 32.8 | 381 |
| Last Detection | C2018 12 01.70493185 24 04.46 +11 44 38.0 | 381 |

Near-Earth Object Tomo-e Gozen ~~Supernova Survey~~

Tomo-e Gozen NEO Viewer

Information of a NEO candidate 42157_126_6



| | | | | | |
|----------------------------|----------------------------|----|---------------|-----|---------------|
| UTC | 2018-12-01 16:55:01.353510 | ra | 5h24m00.3529s | dec | 11d44m32.772s |
| RA,DEC | | | | | |
| Vx | | | | | |
| Vy | | | | | |
| X | | | | | |
| Y | | | | | |
| Detection Threshold | | | | | |
| Machine Learning Threshold | | | | | |

MPC format

| | |
|-----------------|---|
| First Detection | C2018 12 01.70487305 24 00.35 +11 44 32.8 |
| Last Detection | C2018 12 01.70493195 24 04.46 +11 44 38.0 |

Tomo-e Gozen NEO Viewer

Detected Object

| | | |
|----------------------------|---------------|---------------|
| utc | ra | dec |
| 2018-12-01 16:55:01.353510 | 5h24m00.3529s | 11d44m32.772s |

Matched NEOs

| name | ra | dec | Vra ["/min] | Vdec ["/min] |
|--------------------|------|------|-------------|--------------|
| no object detected | None | None | None | None |

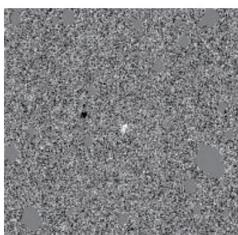
Matched Satellites and debris

| name | residual [arcsec] | ra | dec | elevation [km] | expected speed ["/sec] | shadow |
|----------------|-------------------|------------|------------|----------------|------------------------|--------|
| 0 SL-12 R/B(2) | 199.867757711 | 5:24:13.61 | 11:44:12.8 | 33946.764 | 16.1 | False |

Near-Earth Object Tomo-e Gozen ~~Supernova Survey~~

Tomo-e Gozen NEO Viewer

Information of a NEO candidate 42608_126_2



| | |
|----------------------------|----------------------------------|
| UTC | 2018-12-01 19:06:44.733165 |
| RA,DEC | 05h57m48.46s +11d39m55.0583s |
| Vx | 3.085 [pix/frame], 7.403 ['/sec] |
| Vy | 0.995 [pix/frame], 2.389 ['/sec] |
| X | 1149.0126 [pix] |
| Y | 864.4681 [pix] |
| Detection Threshold | 1.7 |
| Machine Learning Threshold | 0.5 |

MPC format

| | | |
|-----------------|---|-----|
| First Detection | C2018 12 01.79834385 57 48.46 +11 39 55.1 | 381 |
| Last Detection | C2018 12 01.79841295 57 51.20 +11 40 08.3 | 381 |

Near-Earth Object Tomo-e Gozen ~~Supernova Survey~~

The screenshot shows two panels of the Tomo-e Gozen NEO Viewer. The left panel displays a grayscale image of a star field with a small white speck indicating the object's position. To its right is a vertical menu with options: UTC, RA, DEC, Vx, Vy, X, Y, Detection Threshold, and Machine Learning Threshold. Below this is a table titled 'Information of a NEO candidate 42608_126_2' containing the following data:

| | Value |
|-----------------|---|
| First Detection | C2018 12 01.79634395 57 48.46 +11 39 55.1 |
| Last Detection | C2018 12 01.79641295 57 51.20 +11 40 08.3 |

The right panel is titled 'Tomo-e Gozen NEO Viewer' and contains three sections: 'Detected Object', 'Matched NEOs', and 'Matched Satellites and debris'. The 'Detected Object' section shows the detection time (2018-12-01 19:06:44.733165), Right Ascension (5h57m48.46s), and Declination (11d39m55.0583s). The 'Matched NEOs' section shows 'no object detected'. The 'Matched Satellites and debris' section is currently empty.

Summary

Tomo-e Gozen = The world largest video camera (84 CMOS sensors+ 1.0 m telescope)

Suitable specifications to characterize/detect debris

- Wide field-of-view — **20 deg² sky coverage** with 1.2"/pixel
- High sensitivity — stars of **18 mag detected in 2 Hz** observation
- High time-resolution — **2 Hz observation**, higher framerate available by partial readout
- Accurate timestamp — **synchronized with the GPS time**, accurate to ~0.2 ms

Operating with a limited performance / Full operation is scheduled in 2019

Performance of Tomo-e Gozen in debris observations

Detection limits: **~30 cm board & ~3 mm mirror in GEO / ~5 cm namecard in LEO**

Follow-up capability:

sub-second time-resolution lightcurve reveals the shape and motion of debris

Daily moving object survey:

detect ~1,000 high-speed (>1"/s) objects and self follow-up in 2 hours

