

## F2

## GEO デブリの画像処理及び光度変動 Image-processing and light curve of orbital objects around GEO

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○Hiroshi ODA, Hirohisa KUROSAKI, Toshifumi YANAGISAWA (JAXA),  
Makoto TAGAWA (Kyushu Univ.)

スペースデブリ光学観測の画像処理、検出手法、および検出物体の光度変動の解析結果について報告する。観測は地平座標固定モード(静止軌道物体は画像内で静止)で行い、一領域につき露光時間3秒で32枚撮像したものを1データセットとした。これらの画像に対して直線運動検出法を適用することで移動物体を検出し、検出された移動物体に対し測光を行い光度変動を調べた。その結果、検出物体が回転している可能性を示唆する光度変動を示すものが多数確認された。本講演ではこれらの解析結果について報告する。また、スペースデブリの回転を誘起させる機構についても議論する。

We report on image-processing, detection and light curve of space debris around the geosynchronous Earth orbit (GEO). In GEO survey observation, we employ the horizontal coordinate system, and set the exposure time to be 3 seconds. A dataset of an observation region consists of 32 successive light frames. We detect moving objects by applying the uniform linear motion detection method to the dataset, and perform photometry on the images to investigate the light curve. As a result, we found that a lot of the detected objects show the time variation in the light curve which provides information on the rotational state of the detected object. We also discuss the cause of the rotation of orbital objects.

**GEOデブリの 画像処理 及び 光度変動**

**Image-processing and Light curve of Space Debris near GEO**

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Geostationary Earth Orbit(GEO)

2013

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Light curve

Orbital information, distribution, n and Rotational state

Geostationary Earth Orbit(GEO)

2013

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  - ▶ More detailed analysis is on going.

Orbital information, distribution, and **Rotational state**

## Observation Site

### Nyukasa Observatory



#### Dome 1

35cm telescope + CCD  
FOV:  $1.4^\circ \times 1.4^\circ$

**GEO survey**

#### Dome 2

25cm + CCD:  
18cm + CCD:  
**LEO survey**  
**NEO survey**

Introducing and testing  
2 CMOS Cameras



### Chofu Observatory

Tri-Axial Mount  
35cm + CCD  
FOV:  $7.6' \times 6.1'$   
**LEO tracking**



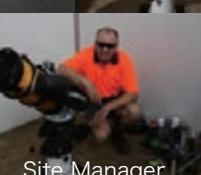
### Australia Remote Obs.

18cm ( $\rightarrow$  25cm) + CCD  
FOV:  $3.17^\circ \times 3.17^\circ$

**GEO survey**  
**NEO survey**



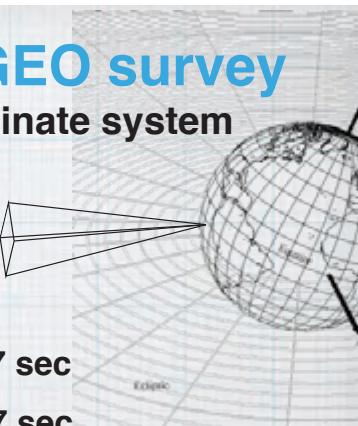
Perspective of the sky



## Observation and Dataset for GEO survey

\*We employ the horizontal (topocentric) coordinate system

- ▶ Stars move horizontally
- ▶ Perfect GEO objects are stationary.

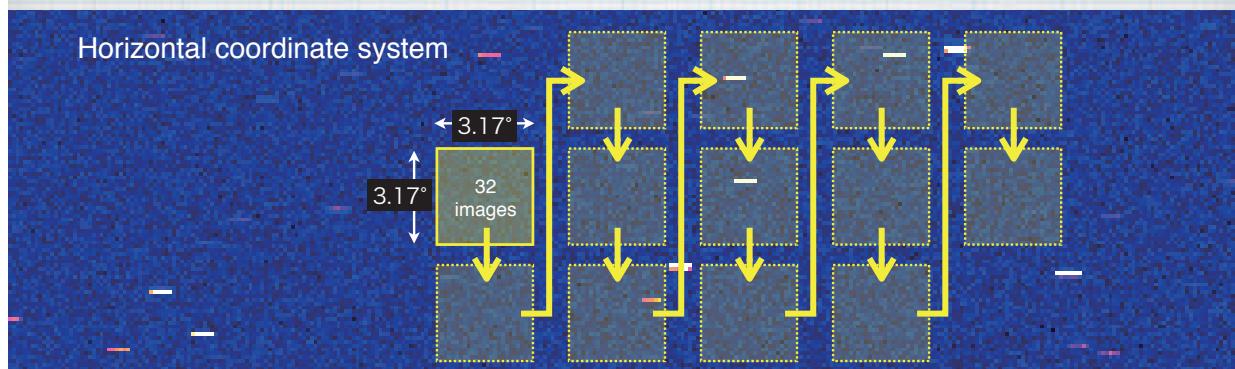


\*Time interval: 3 sec exposure + Readout time.

- ▶ ARO: 3 sec exposure + 1.7 sec readout ~ 4.7 sec
- ▶ Nyukasa: 3 sec exposure + 2.7 sec readout ~ 5.7 sec

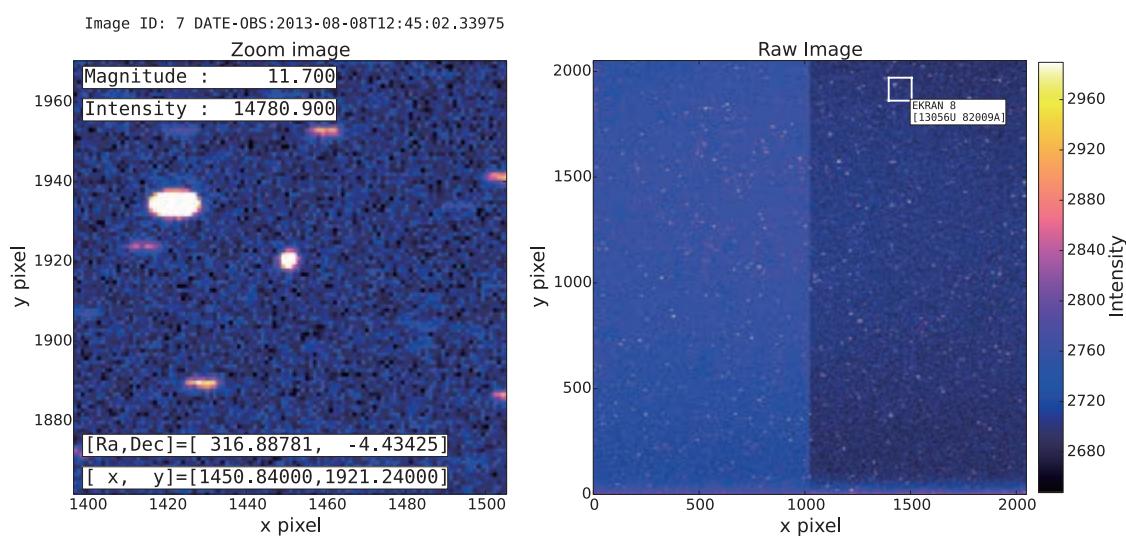
\*Duration: (4.7 or 5.7 sec) x 32 images ~150 sec

Note: The dataset is optimised for detection efficiency but light curves



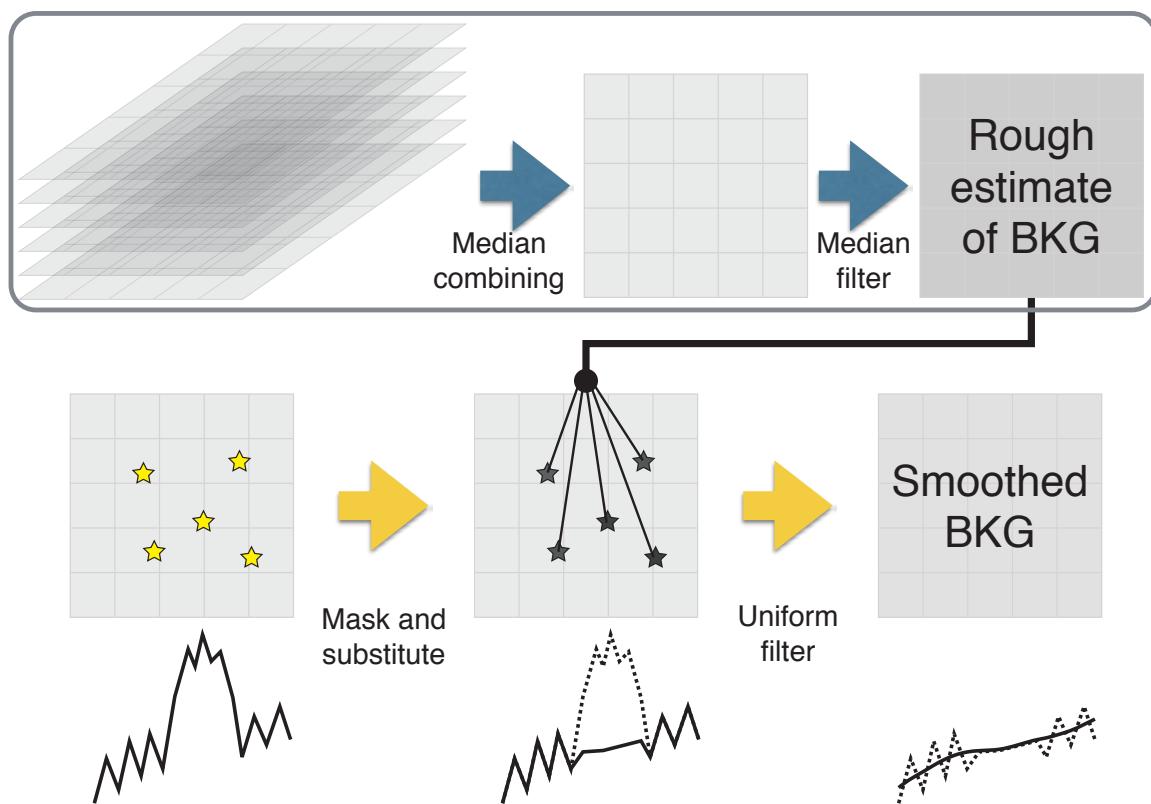
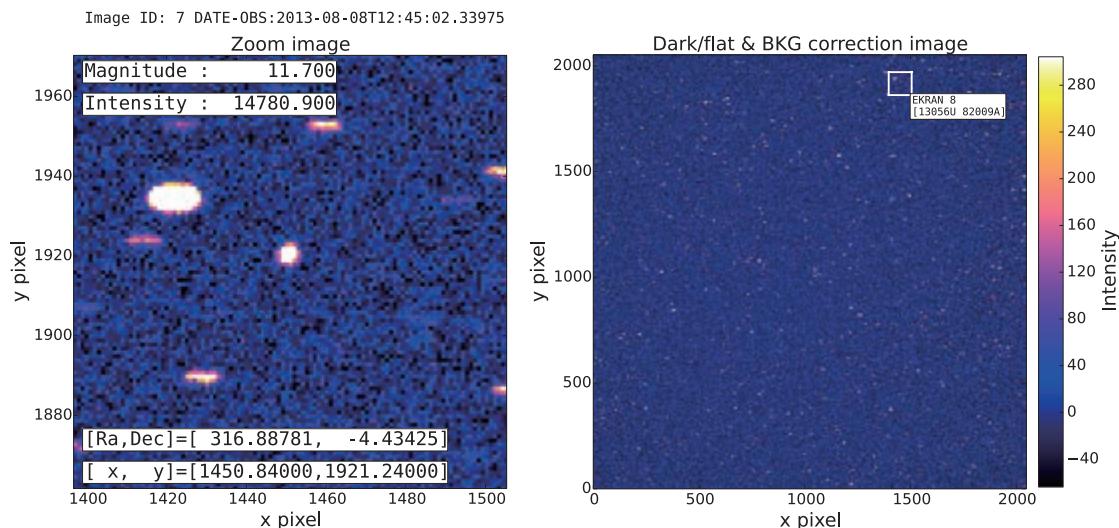
## Image-processing

- \* Raw image
- \* Dark-Bias subtraction, Flat correction, BKG subtraction
- \* Diurnal motion object (star trail) masking



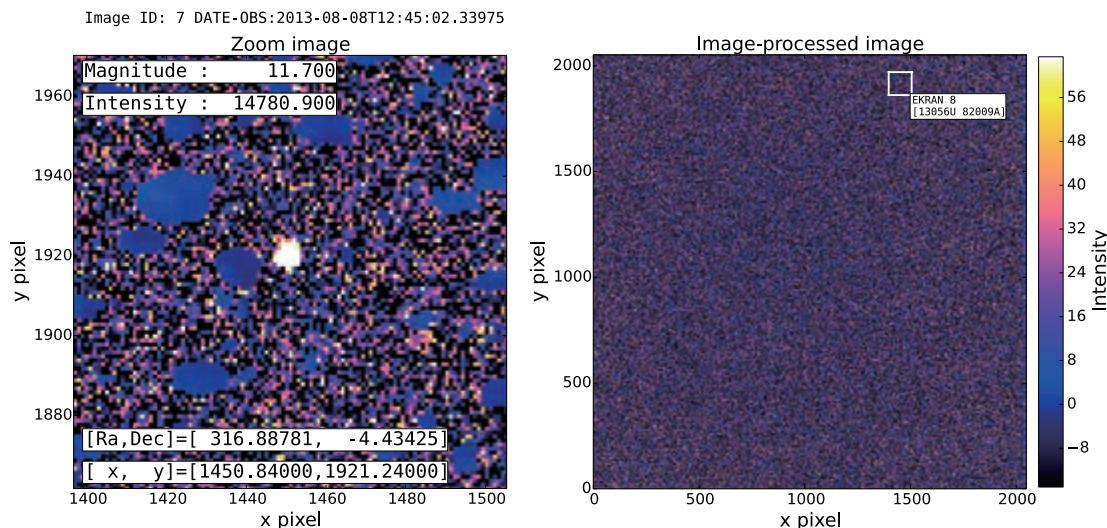
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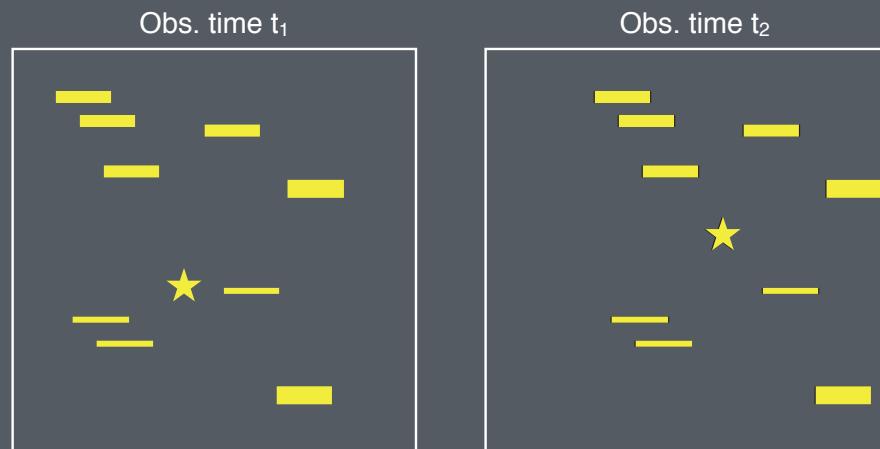


# Image-processing

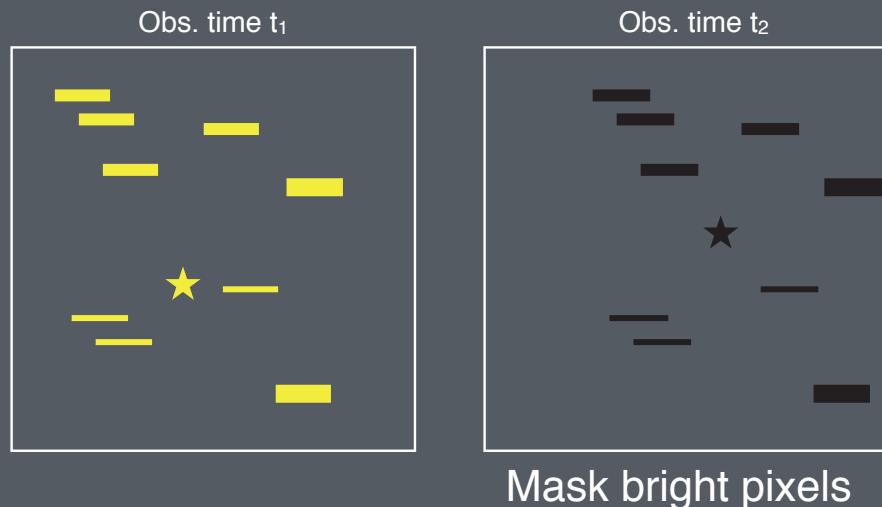
- \* Raw image
- \* Dark-Bias subtraction, Flat correction, BKG subtraction
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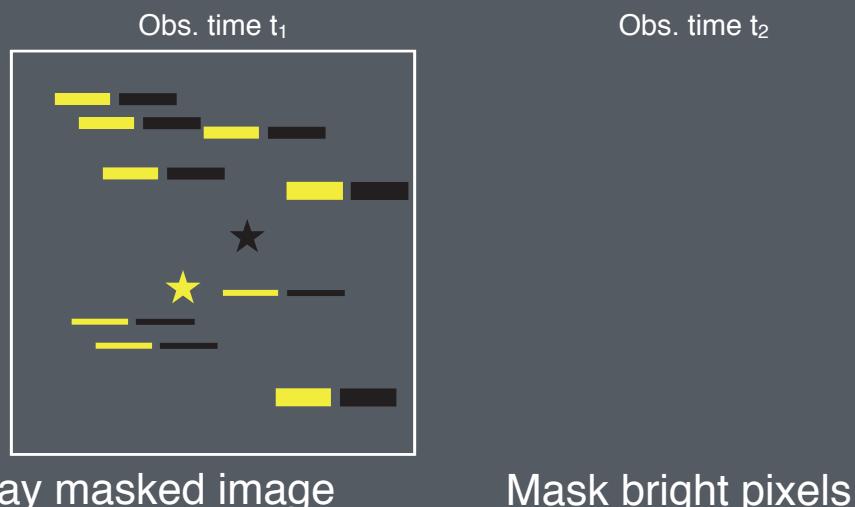
Diurnal motion object (star trail) masking  
For the convenience in detection of orbital objects,  
we want to mask star trail...



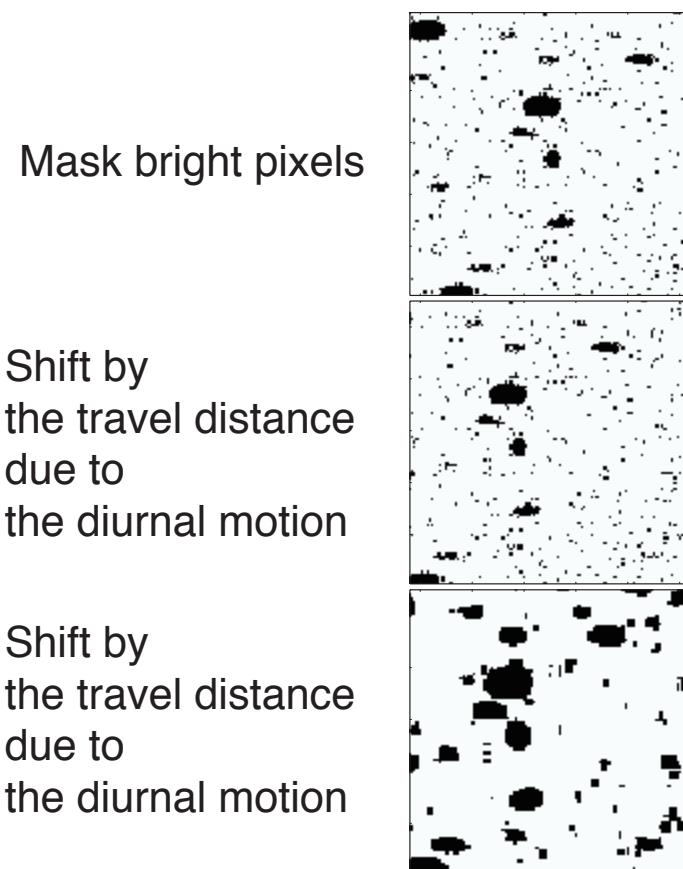
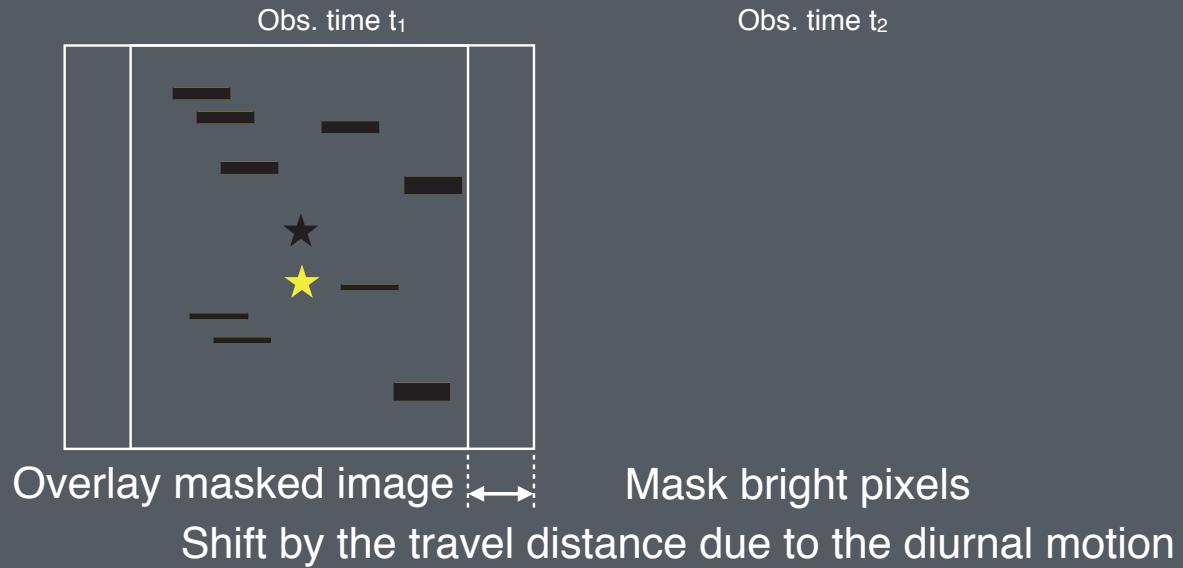
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Diurnal motion object (star trail) masking  
For the convenience in detection of orbital objects,  
we want to mask star trail...



## Detection algorithm: Uniform linear motion detection



limited by the computational resources

▶ **Step1**  
Select 500 candidates based on

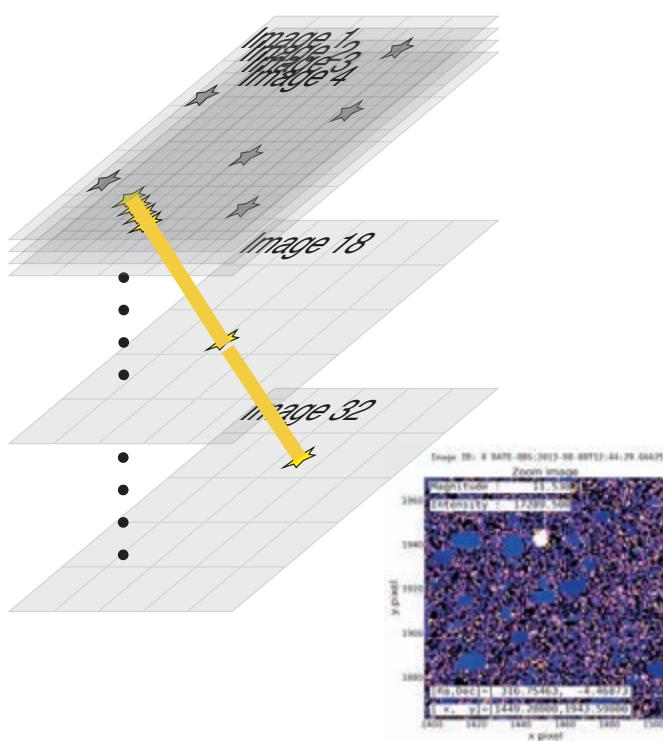
- shape (blurred by atmospheric turb.)
- Intensity (brightest 500)

At this step,  
noise, cosmic rays, etc... are included.

▶ **Step2**  
Search objects showing the uniform linear motion

- 9 out of first 18 light frames

## Detection algorithm: Uniform linear motion detection



limited by the computational resources

▶ **Step1**  
Select 500 candidates based on

- shape (blurred by atmospheric turb.)
- Intensity (brightest 500)

At this step,  
noise, cosmic rays, etc... are included.

▶ **Step2**  
Search objects showing the uniform linear motion

- 9 out of first 18 light frames

▶ **Step3 (for lightcurve)**  
extrapolate the detected path  
to the **32th image** and follow-up search

# Photometry

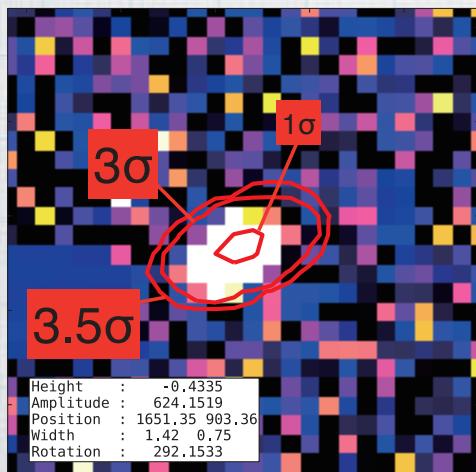
Moving objects leave trailed image (**not circle and ellipse**)

**Extract pixels adequate for photometry using the 2D-Gaussian fit**

\*Step 1: Crop region surrounded by  **$3.5\sigma$**

→ apparently inadequate pixels are excluded.

\*Step 2: Extract pixels whose value greater than the value at  **$3\sigma$**



**Total intensity:**

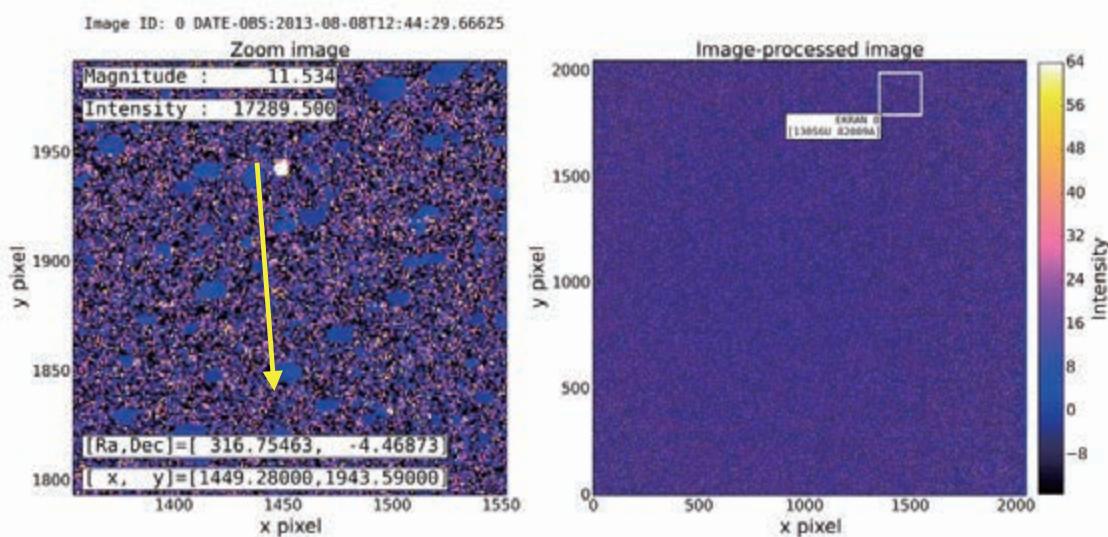
Adding up  
the extracted pixels



Image ID : 2  
Threshold : 6,5002  
Peak : 544,9337  
Total : 4166,6298

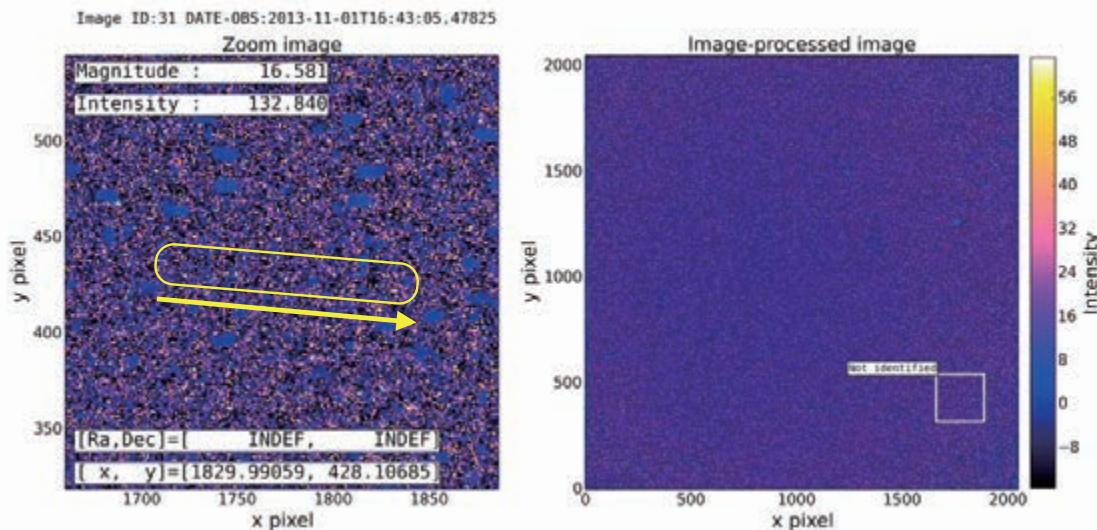
## Example of a bright object

2013/08/08, region 027, object 0:  
Mean mag. 11.79



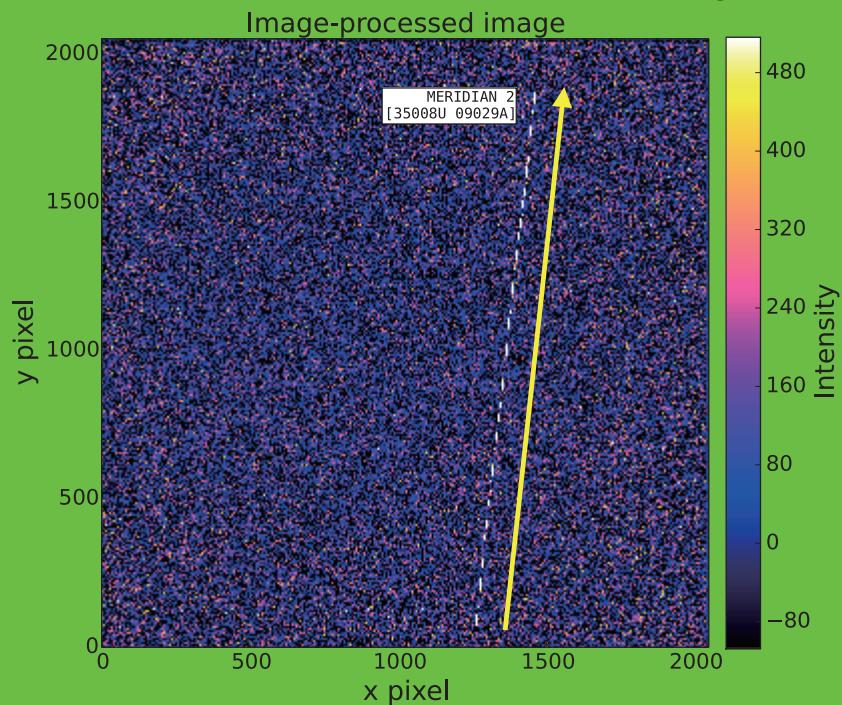
## Example of a faint object

2013/11/01, region 049, object 0:  
Mean mag. 15.11

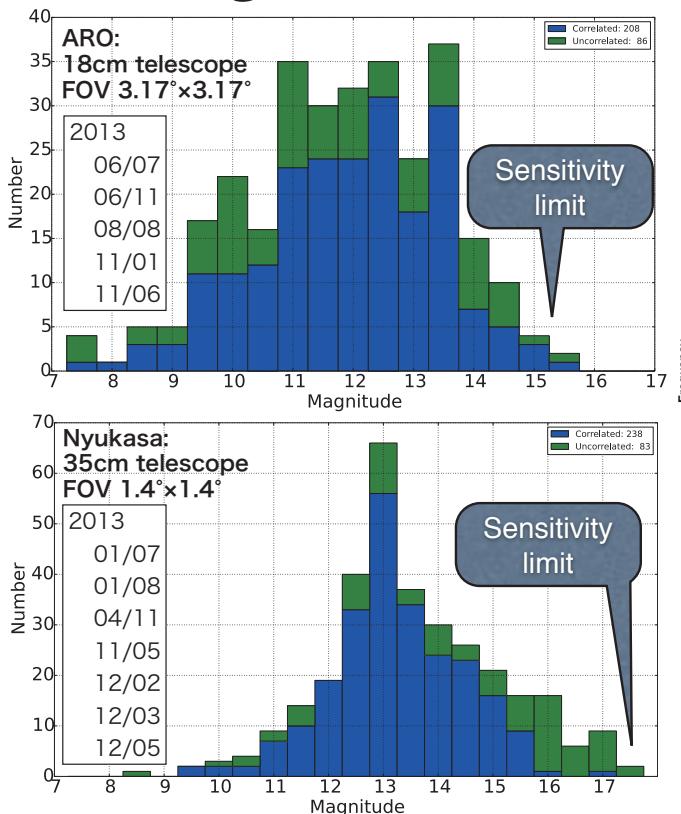


## Example of a fast (and bright) object

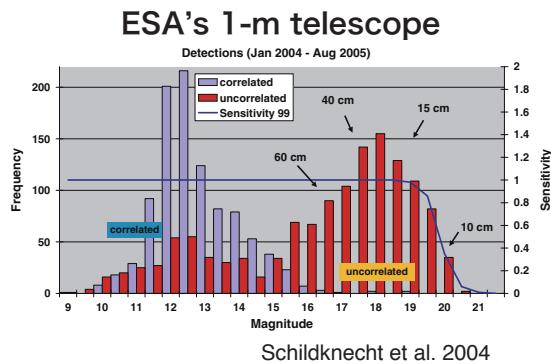
2013/11/01, region 058, object 0:  
Velocity = 21.85 pix/sec (~ 0.034 deg/sec)



# Magnitude-Number distribution



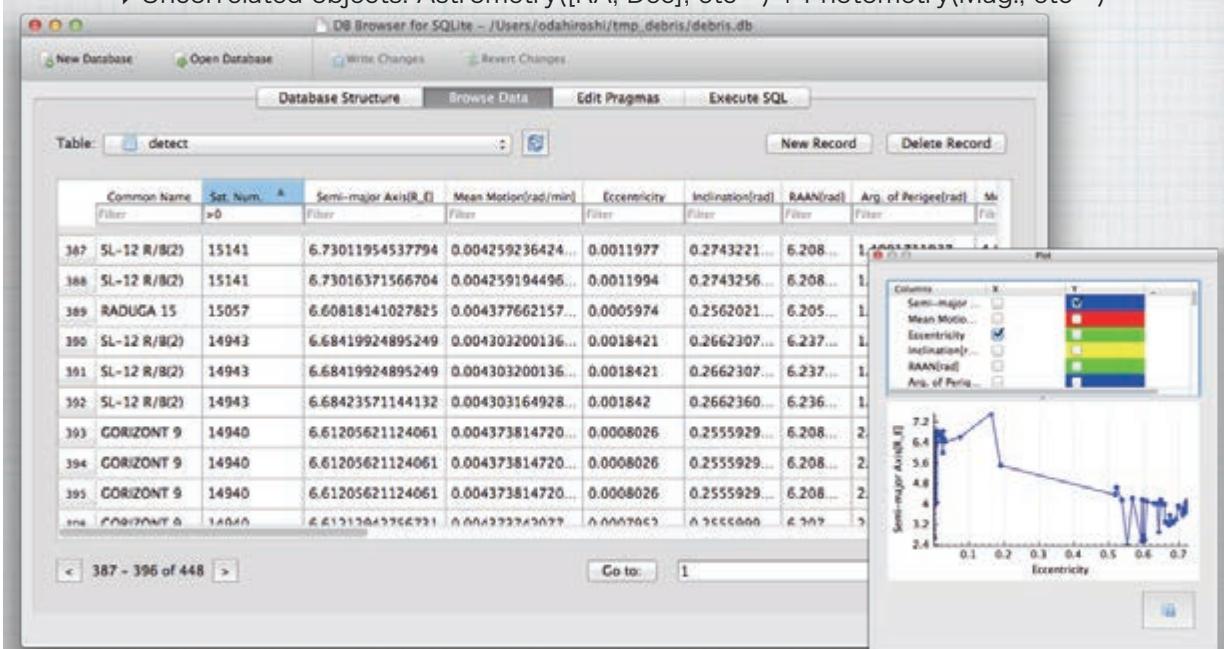
Peak at ~12-13 Mag.  
▶ reflects the size distribution in the catalog.



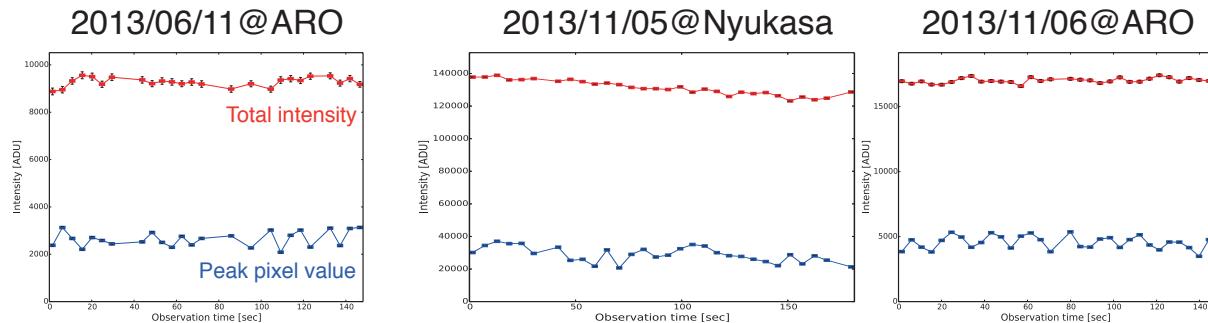
Note: A lot of detected object shows a time variation in the light curve.  
The “mean” mag. could not represent the proper size.

## Database Management

- \* Database Language: SQLite
  - ▶ Python standard library (Our codes are written in Python)
- \* Database Structure
  - ▶ Correlated objects: Orbital elements in TLE catalog + Astrometry + Photometry
  - ▶ Uncorrelated objects: Astrometry([RA, Dec], etc...) + Photometry(Mag., etc...)



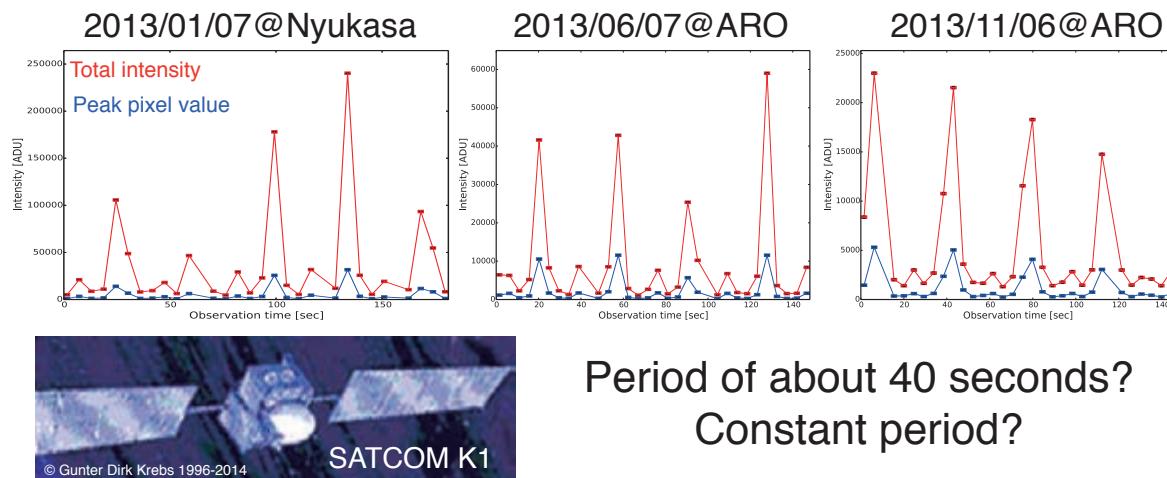
# Light curve: Stable Example



Correlated: JCSAT 5 [25067] - communication satellite

Date	Semi-major Axis[R]	Eccentricity	Inclination [rad]	RAAN [rad]	Argument of Perigee[rad]	Mean Mag.
06/11	6.61	0.00046	0.0484	1.214	0.17	11.74
11/05	6.61	0.00053	0.0537	1.191	2.74	11.11
11/06	6.61	0.00053	0.0537	1.191	2.75	10.96

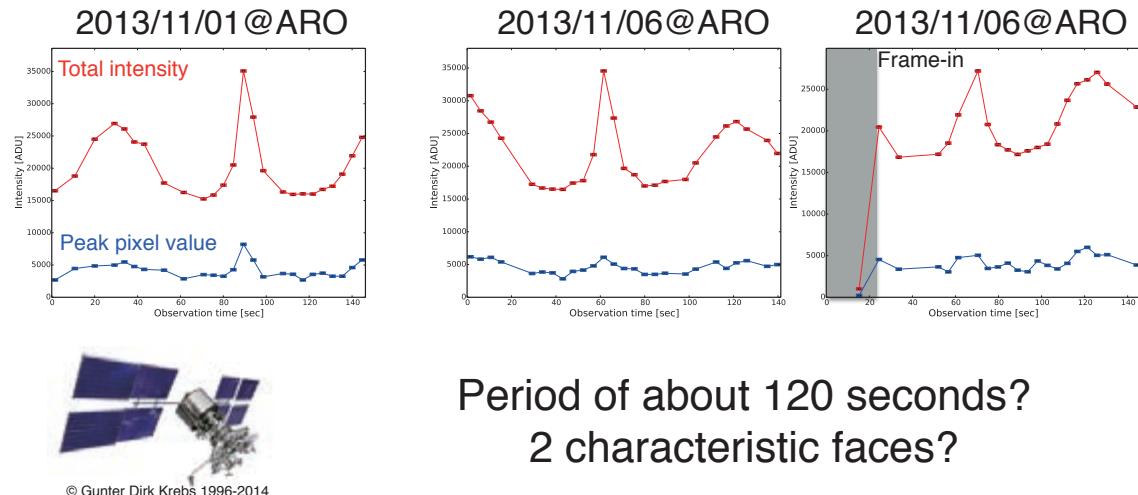
# Light curve: Periodic Oscillation (Spike-like) Example



Correlated: SATCOM K2 [16276] - communication satellite, de-orbited in 2002

Date	Semi-major Axis[R]	Eccentricity	Inclination [rad]	RAAN [rad]	Argument of Perigee[rad]	Mean Mag.
01/07	6.64	0.0008	0.224	0.678	2.00	11.77
06/07	6.64	0.0009	0.229	0.647	2.51	12.71
11/06	6.64	0.0012	0.232	0.615	2.62	12.76

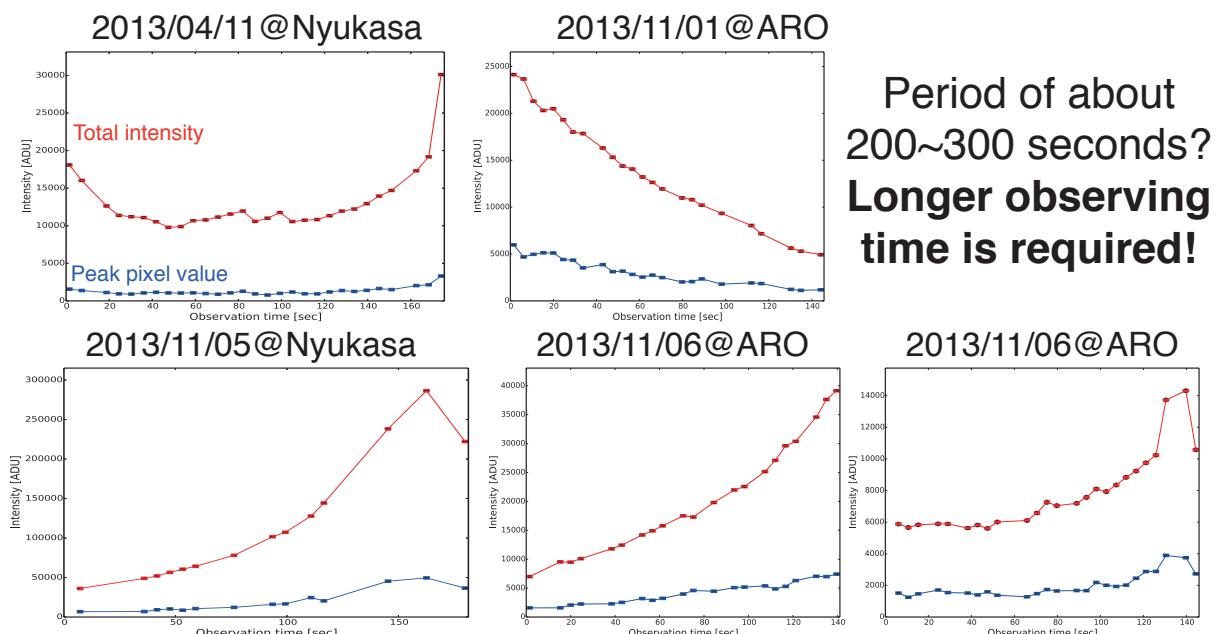
## Light curve: (Moderately) Long Periodic Oscillation Example



Correlated: EXPRESS 1 [23319] - communication satellite, launched in 1994

Date	Semi-major Axis[R]	Eccentricity	Inclination [rad]	RAAN [rad]	Argument of Perigee[rad]	Mean Mag.
11/01	6.63	0.00074	0.1994	0.757	1.948	10.86
11/06	6.63	0.00073	0.1996	0.756	1.951	10.70
11/06	6.63	0.00073	0.1996	0.756	1.951	10.91

## Light curve: (Likely) Long Periodic Oscillation Example

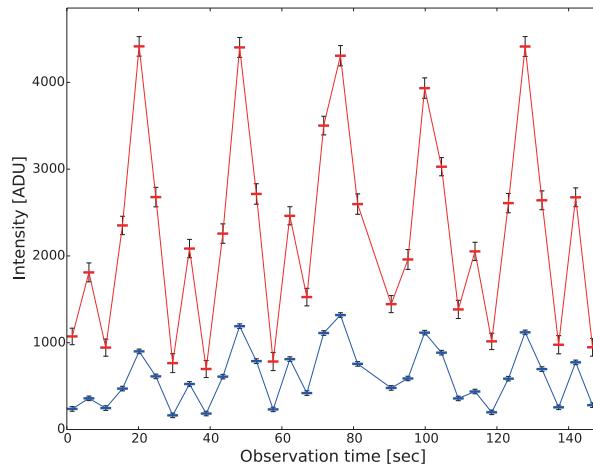


Correlated: RADUGA 1-7 [28194] - communication satellite, launched in 2004

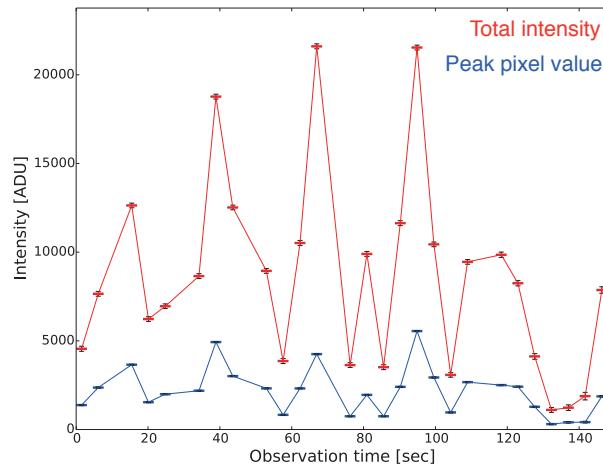
Date	Semi-major Axis[R]	Eccentricity	Inclination [rad]	RAAN [rad]	Argument of Perigee[rad]	Mean Mag.
04/11	6.606	0.0002635	0.1230	1.1023	0.1784	13.12
11/01	6.610	0.0004036	0.1301	1.0568	1.3865	11.71
11/05	6.610	0.0003984	0.1302	1.0561	1.4027	11.00
11/06	6.610	0.0003984	0.1302	1.0561	1.4027	11.32
11/06	6.610	0.0003984	0.1302	1.0561	1.4027	11.77

# Light curve: Rapid Oscillation Example

2013/06/07@ARO



2013/06/11@ARO



Period of about less than 5~10 seconds?

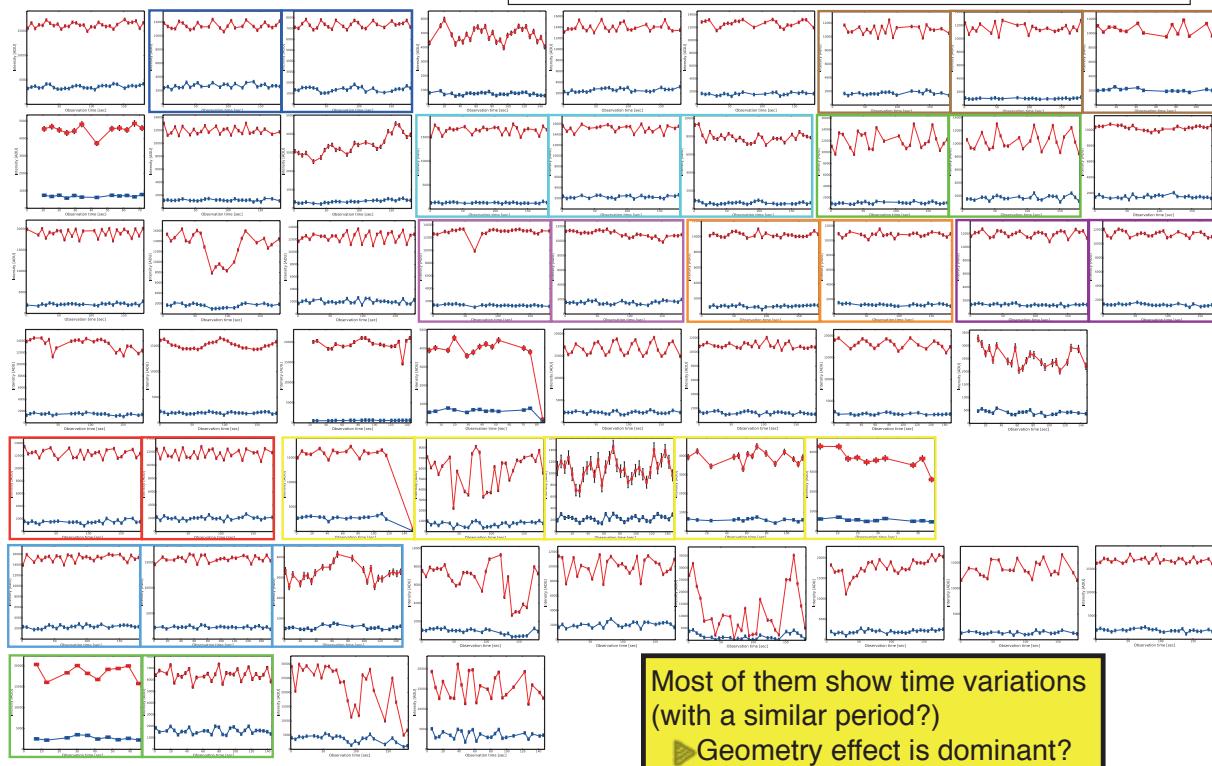
**Shorter observation time interval is required!**

Correlated: ARABSAT 3A [25638] - communication satellite, launched in 1999

Date	Semi-major Axis[R]	Eccentricity	Inclination [rad]	RAAN [rad]	Argument of Perigee[rad]	Mean Mag.
06/07	6.615	0.000467	0.0707	1.1451	5.421	11.74
06/11	6.615	0.000478	0.0708	1.1446	5.406	12.11

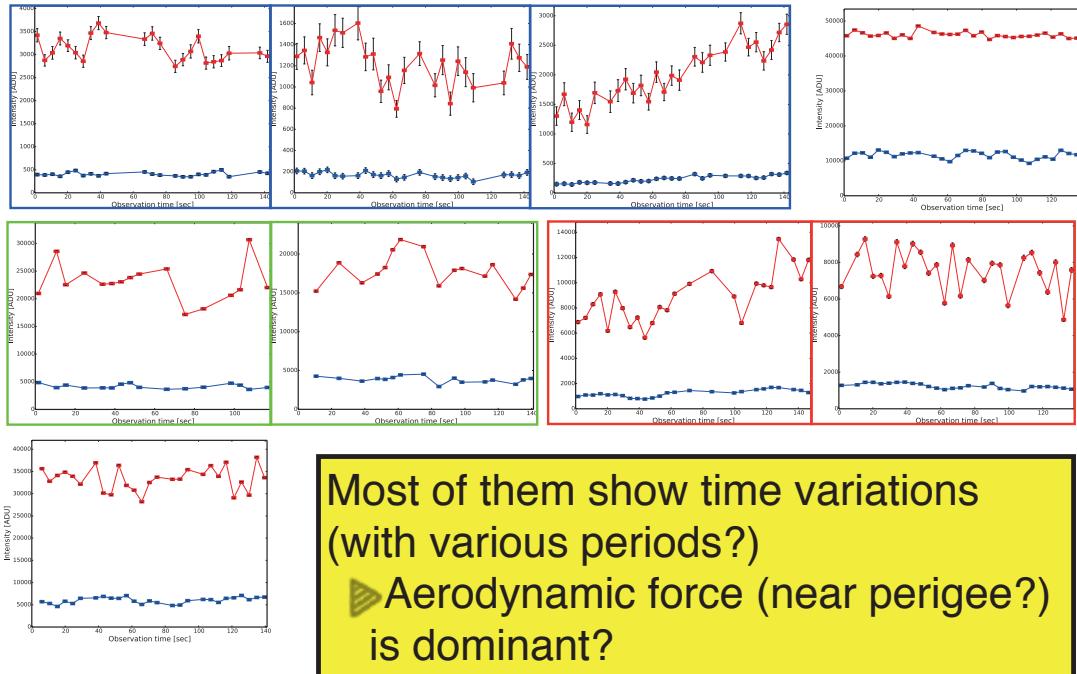
# Light curve: SL-12 R/B(2) series

$a \sim 6.5\text{--}6.7 [R_E]$ ,  $e \sim 0.0043\text{--}0.0045$



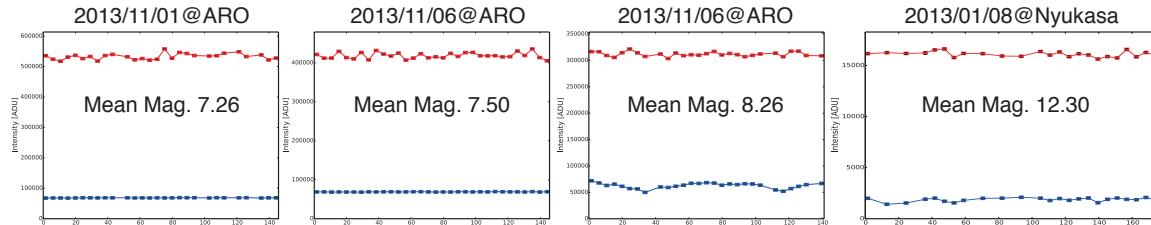
# Light curve: ARIANE 5 R/B series

$a \sim 3.5\text{-}3.8 [R_E]$ ,  $e \sim 0.71\text{-}0.72$



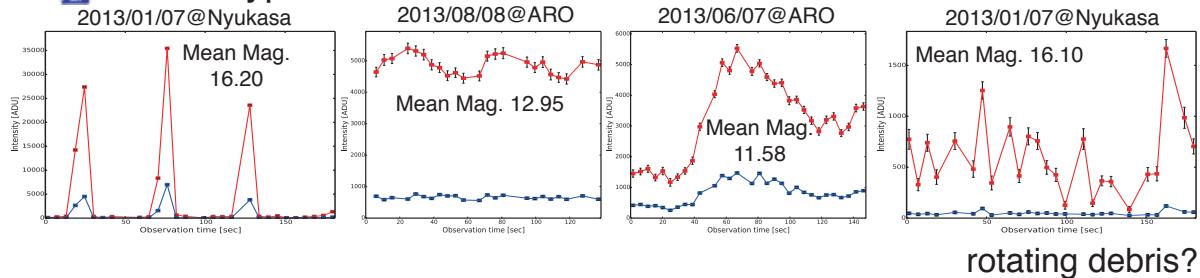
# Light curve: Uncorrelated Objects

Stable and bright



possibly operated, but just not listed in the catalog for some reasons?

Various type of time variation



# Summary

- **GEO survey observation**
  - 18cm telescope + CCD @ ARO
  - 35cm telescope + CCD @ Nyukasa
  - 32 images in a region (optimised for detection efficiency)
- **Image-processing, detection algorithm**
  - Dark/Flat, BKG subtraction, diurnal motion (star trail) masking
  - Uniform linear motion detection
  - Photometry (for motion blurred objects)
- **Detection result**
  - ARO: 208 correlated + 86 uncorrelated in 5 night data
  - Nyukasa: 238 + 83 in 7 night data
  - Database management (using SQLite)
- **Light curve**
  - A lot of detected objects show a time variation
    - Longer observing time is required for long periodic oscillation.
    - Shorter time interval is required for short periodic oscillation.
  - Optimised observation and detailed analysis is on going.

# Future works

- We replaced 18cm telescope with 25cm telescope in June 2014
  - Sensitivity limit must be improved (by a magnitude of 1?)
- **Improve detection algorithm: Stacking method**
  - Stack images shifted along to the “**all possible predicted**” moving direction.
    - Detection limit is expected to be improved by a magnitude of 2 empirically.
  - However, huge computational resources are required...
  - We plan to accelerate it by making use of GPU(e.g., NVIDIA Tesla K20).