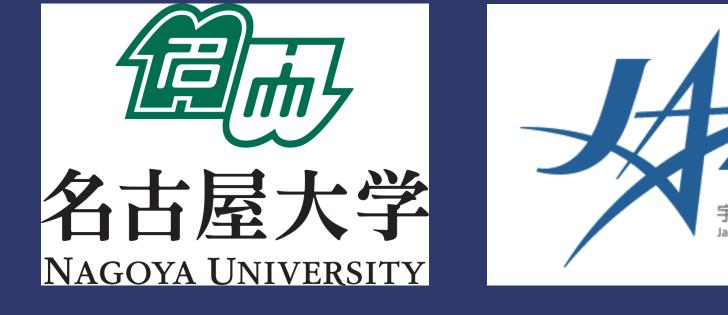
# 無飛翔型MEID機構の提案と月惑星探査機着陸脚への応用

Proposal of Non-Flying-Type MEID Mechanism and Its Application to Lunar/Planetary Exploration Spacecraft Landing Gear

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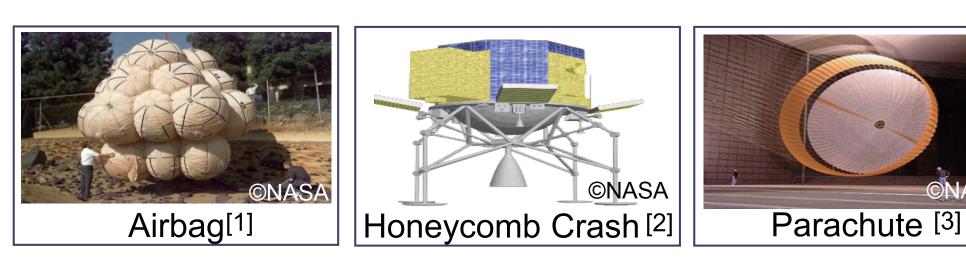


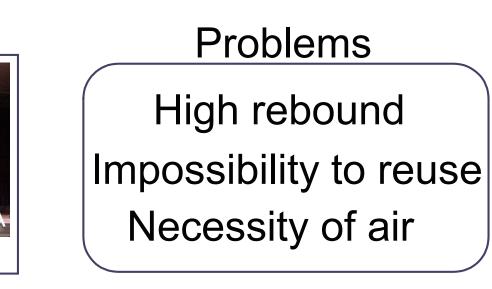
This study discusses a lunar/planetary exploration spacecraft landing mechanism using NFMEID. NFMEID can exchange the vertical shock into the spacecraft to the rotary momentum of the landing gear and damper masses. Further, NFMEID can be applied to shock response control of the general mechanical structures because of its compact structure. This report shows the effectiveness of NFMEID in vertical landing case.

# Background

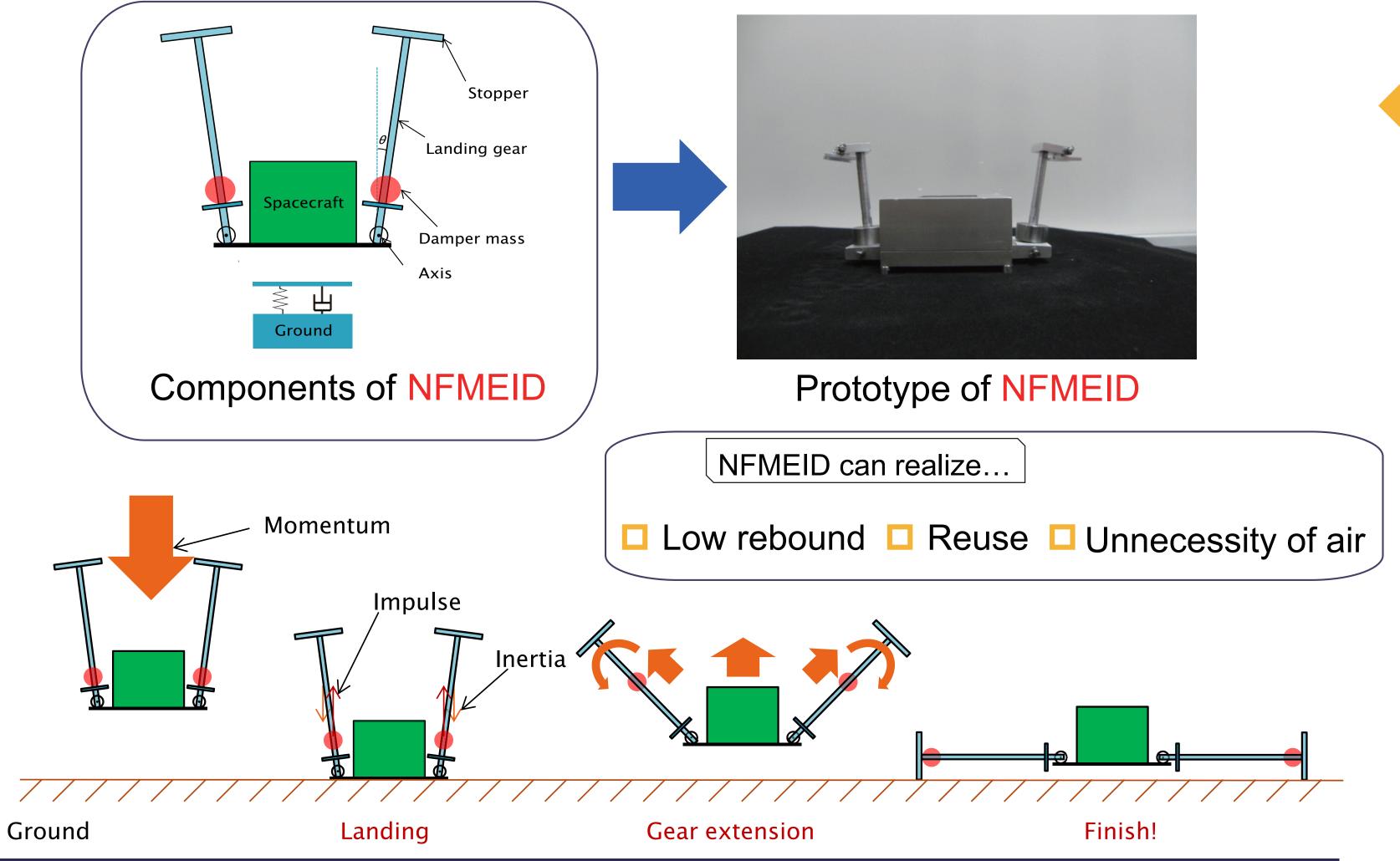
## Simulation results

- Necessity for detailed Lunar/Planetary explorations by spacecraft
  - Requirement for shock response control
- Previous methods and their problems

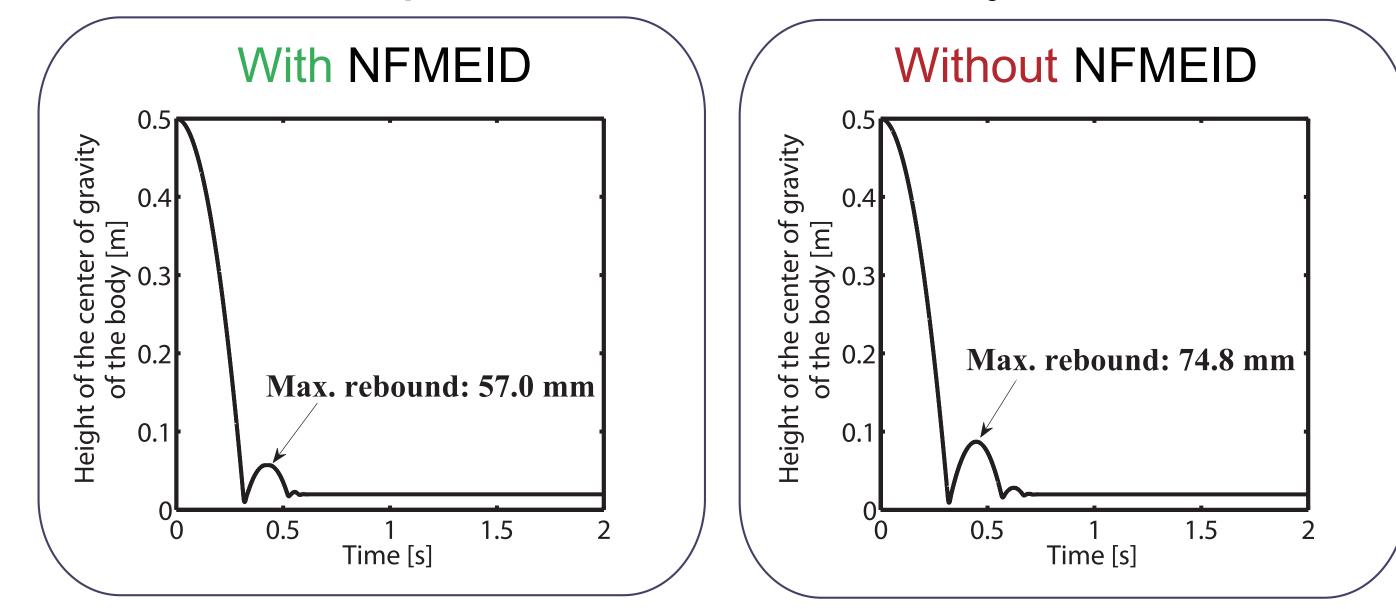




#### **NFMEID** Non-Flying-Type Momentum Exchange Impact Damper



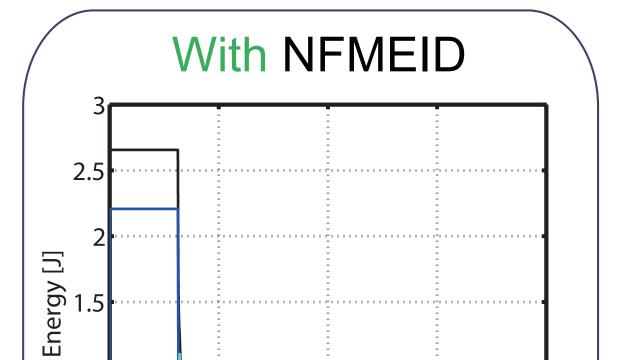
Vertical displacement of the body

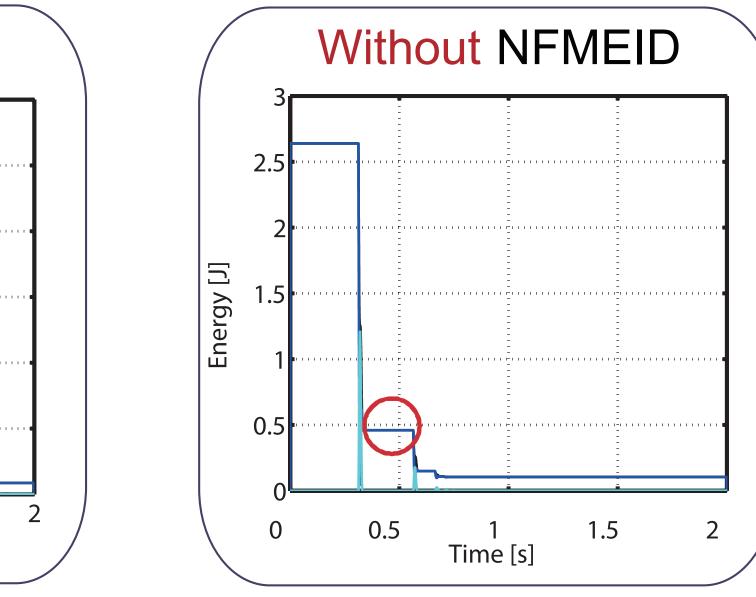


暫定的なパラメータを用いて、リバウンドを約25%抑制できた.

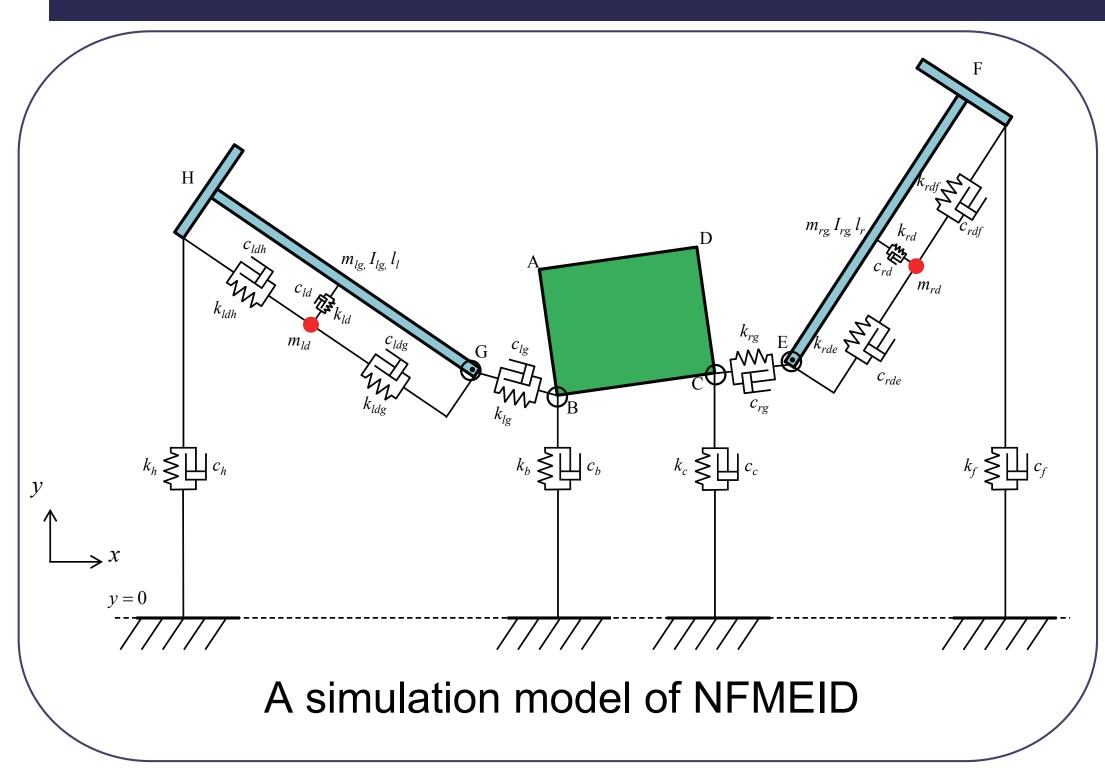
□ NFMEID can reduce the rebound to around 25%.

Mechanical energy of the system

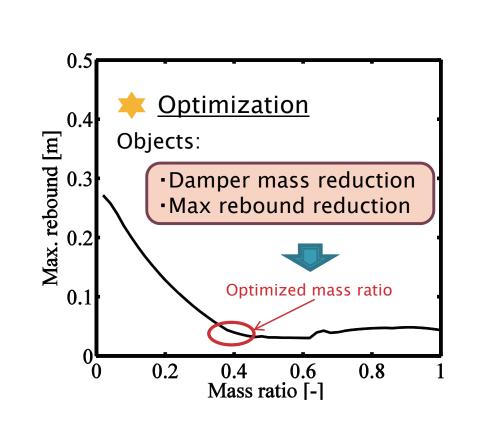




# Model for simulation



$k_{c}$	1.0×10 <sup>4</sup>					
C <sub>c</sub>	Vertical damping between C and ground [N·s/m]	30				
$k_{f}$	Vertical stiffness between F and ground [N/m]	1.0×10 <sup>4</sup>				
$C_{f}$	Vertical damping between					
$k_h$	Vertical stiffness between H and ground [N/m]	1.0×10 <sup>4</sup>				
C <sub>h</sub>	Vertical damping between H and ground [N·s/m]	30				
$k_{rg}$	Stiffness of the restriction between the body and right gear [N/m]	1.0×10 <sup>4</sup>				
C <sub>rg</sub>	Damping of the restriction between the body and right gear [N·s/m]	100				
$k_{lg}$	Stiffness of the restriction between the body and left gear [N/m]	1.0×10 <sup>4</sup>				
C <sub>lg</sub>	$C_{lg}$ Damping of the restriction between the body and left gear [N·s/m]					
k <sub>rd</sub>						
$C_{rd}$	10					
k <sub>ld</sub>	1000					
C <sub>ld</sub>	Damping of the restriction between left gear and damper mass [N·s/m]	10				
k <sub>rde</sub>	Stiffness of the restriction between E and right damper mass [N/m]	1000				
C <sub>rde</sub>	Damping of the restriction between E and right damper mass [N·s/m]	5.0				
k <sub>rdf</sub>	Stiffness of the restriction between F and right damper mass [N/m]	1000				
C <sub>rdf</sub>	Damping of the restriction between F and right damper mass [N·s/m]	5.0				
k <sub>ldg</sub>	Stiffness of the restriction between G and left damper mass [N/m]	1000				
C <sub>ldg</sub>	Damping of the restriction between G and left damper mass [N·s/m]	5.0				
$k_{_{ldh}}$	Stiffness of the restriction between H and left damper mass [N/m]	1000				
C <sub>ldh</sub>	Damping of the restriction between H and left damper mass [N·s/m]	5.0				



0.5

0.5

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> Mass Ratio= Right + Left damper masses Body

 ダンパ質量の割合が増えるにつれ、リバウンド量が 抑制されているため、NFMEIDの有効性が確認できる.

□ This figure shows NFMEID's effectiveness.

Considering the damper mass reduction, and maximum rebound reduction, the optimized mass ratio is 30~40%.

Black: entire system Blue: the body Red: landing gears Light blue: springs Green: damper masses ●本体の力学的エネルギーを散逸させることができた.

□ NFMEID can distribute the body's energy to other parts.

### The ratio of damper masses

1.5

Time [s]

### Initial height : 0.5 m

						rae		
$m_b$	Body mass [kg]	0.45	$I_{lg}$	Moment of inertia of left gear [kg·m <sup>2</sup> ]	1.0×10 <sup>-6</sup>	C <sub>rde</sub>	Damping of the restriction between E and right damper mass [N·s/m]	5.0
m <sub>rg</sub>	Right gear mass [kg]	0.0034	l	Width of the body [m]	0.10	k <sub>rdf</sub>	Stiffness of the restriction between F and right damper mass [N/m]	1000
m <sub>rd</sub>	Right damper mass [kg]	0.044	$l_{rg}$	Length of right gear [m]	0.060	C <sub>rdf</sub>	Damping of the restriction between F and right damper mass [N·s/m]	5.0
m <sub>lg</sub>	Left gear mass [kg]	0.0034	$l_{lg}$	Length of left gear [m]	0.060	k <sub>ldg</sub>	Stiffness of the restriction between G and left damper mass [N/m]	1000
m <sub>ld</sub>	Left damper mass [kg]	0.044	h	Thickness of the body [m]	0.050	C <sub>ldg</sub>	Damping of the restriction between G and left damper mass [N·s/m]	5.0
$I_b$	Moment of inertia of the body [kg·m <sup>2</sup> ]	4.0×10 <sup>-4</sup>	k <sub>b</sub>	Vertical stiffness between B and ground [N/m]	1.0×10 <sup>4</sup>	k <sub>ldh</sub>	Stiffness of the restriction between H and left damper mass [N/m]	1000
$I_{rg}$	Moment of inertia of right gear [kg·m <sup>2</sup> ]	1.0×10 <sup>-6</sup>	C <sub>b</sub>	Vertical damping between B and ground [N·s/m]	30	C <sub>ldh</sub>	Damping of the restriction between H and left damper mass [N·s/m]	5.0

### Conclusion

- NFMEID can convert the vertical momentum of the body to the rotary momentum of landing gears and damper masses.
- To improve the NFMEID's performance, parameter optimization should be investigated.
- For detailed investigation, the falling simulation onto slope and step should be practiced in the future.

#### References

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  - <a href="http://www.esa.int/SPECIALS/ExoMars/SEM2QQ3MDAF-0.html">http://www.esa.int/SPECIALS/ExoMars/SEM2QQ3MDAF-0.html</a>, (accessed 2014-6-4).
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