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超小型深宇宙探査実証機PROCYONの軌道設計及び運用状況

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1. Introduction

PROCYON (PRoximate Object Close flyby with Optical Navigation) is a 50kg-class micro-spacecraft developed by the University of Tokyo and the Japan Aerospace Exploration Agency (JAXA), based on the expertise acquired on past satellites developed at The University of Tokyo[1-3]. PROCYON was launched in an Earth resonant trajectory on December 3rd, 2014 as a secondary payload with Hayabusa 2 mission.



The mission objective is to demonstrate micro-spacecraft bus technology for deep space exploration and proximity flyby to asteroids performing optical measurements.

2. Mission Objectives and Scenario

Success Criterion: Summing system is adopted.

	Success Criterion	Point	Sum		
Primary Mission	Success in the power generation, thermal control, attitude control (by CGJ), communications, and orbit determination in deep space	50	50		
<u>Objective</u>	Success in the Operation of MIPS in deep space Achievement of a certain level of velocity increase by MIPS	20 30	70 100		
	Success in the communication with SSPA made from GaN Success in a differential VLBI technology for deep space		150 200		
Secondary <u>Mission</u> Objective	Return to Earth one year later by the trajectory control Success in Earth swing-by and injection into transfer phase	100 50	300 350		
	Approach to the asteroid by the telescope from far Approach to the asteroid by the optical navigation, Success in asteroid imaging as an object having a size		500		
	Success in a continuous imaging of asteroids from close range by the tracking control				
CGJ : Cold Gas Jet MIPS : Miniature Ion Propulsion System GaN : Gallium nitride SSPA: Solid State Power Amplifier VLBI : Very Long Baseline Interferometry					
Earth Gravity Assist (EGA) A (3) Proximity Flyl (1) Earth-to-Earth phase (2) Transfer phase			Flyby		
Asteroid target select dependence on laun	Lor 2 year Less than 1 year More than 3 days (around the days and the days around the days aro	14,5 days			
Thruste	r: MIPS Thruster: MIPS (almost Ballistic) Thruster: Cold G	as Jet (C	(iJ)		

- Target asteroids are selected from the full asteroid database of the IAU Minor Planet Center with more than 600,000 asteroids. System Requirements and Operation Constraints make
- the trajectory design complicate.

Orbit Determination: R&RR Orbit Determination: R&RR

Trajectory Control Method:

PROCYON has I-COUPS (Ion thruster and COld-gas thruster Unified Propulsion System) developed for PROCYON to use 2 propulsion methods according to situations:

MIPS: Low Thrust & High Isp — For Interplanetary maneuver CGJ: High Thrust & Low Isp — For Close approach operation

There is a possibility that some parameters differ from assumptions. Some aspects of the operation and limited information make estimations of actual parameters complicate.

3. Mission characteristic

Most of the mission design aspect are driven by subsystem requirements. Snacecraft

			opaccelait			
	Earth to Earth phase	Transfer phase	Mass	Initial Total Mass[kg]: 66.928		
Operation	•MIPS Operation Duty $d_{IPS} \leq 0.7$ (Constraint)			Fuel Mass(Xe)[kg]: 2.5		
Power	 Solar energy flux Es ≥ 812[W/m²] 	 Solar energy flux E_s ≥ 585 [W/m²] 	Structure	0.55m × 0.55m × 0.67m (SAPs close 1.5m × 1.5m × 0.67m (SAPs open)		
	(MIPS Operation mode)	IPS Operation mode) (CGJ Operation mode) * Earth Distance D⊆ ≤ 0.57 [AU] at Proximity Flyby phase • Declination of the > Declination of the spacecraft from the Usuda Deep Space Center (UDSC) Soci ≥ 5.6.3 [*]	Attitude Control System	Reaction Wheels (× 4) 3-axis Fiber Optic Gyro (× 1) Star Tracker (× 1)		
Commu- nication						
				Non-spin Sun Sensors (×5)		
				1-axis Rotatable Telescope (×1) (asteroid obs. and optical nav.)		
Thermal		$\bullet 0.9[AU] \leq Solar$ Distance Ds $\leq 1.5[AU]$	Miniature Ion Propulsion System (MIPS) using Xe	Thrust[mN]: 0.30 Isp[s]: 1000.0		
Asteroid Flyby		Target asteroid can be observable 3days before the closest approach Relative velocity with the asteroid Vrel≦30[km/s]	Cold Gas Jet (CGJ) using Xe (×8)	Thrust[mN]: 22.0 Isp[s]: 24.5		
			Communication System	X band TT&C, 1 X-HGA, 1 X-MGA, 2 X-LGA(Downlink), 2 X-LGA(Uplink)		

4. Trajectory Design Result and Current Status

PROCYON is now in Earth-to-Earth transfer phase. The launch result and the ion engine performance are being analyzed. Together with the orbit determination data, the trajectory is redesigned to minimize the propellant mass with jTOP, a in-house trajectory optimization that implements a direct method.

Orbital E	lements of Pl	ROCYON	(J2000	Ecliptic Cod	ordinate)	
						_

Semi-major axis [km]	Eccentricity	Right ascension of the ascending node[deg]	Inclination [deg]	Argument of perigee[deg]
1.4988×10^8	0.0874	250.6	6.820	95.59

Example of a trajectory to a candidate of target asteroids:





Coordinate

Example of Trajectory in Sun-Earth fixed rotating frame

Current Status:

PROCYON has almost completed its "Primary Mission Objective". The acceleration test by MIPS (Miniature Ion Propulsion System) is ongoing and PROCYON's acceleration was observed.

Some parameters of PROCYON (e.g. MIPS and CGJ) will be updated by using orbit determination data and telemetry data for the more precise trajectory design and Proximity Flyby phase.

References

Orbit Determination: Optical Image

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